

Science motivations and introductory remarks

GSA 2019

J Ramón Arrowsmith School of Earth and Space
Exploration
Arizona State University

Christopher J. Crosby
UNAVCO



OpenTopography
High-Resolution Topography Data and Tools

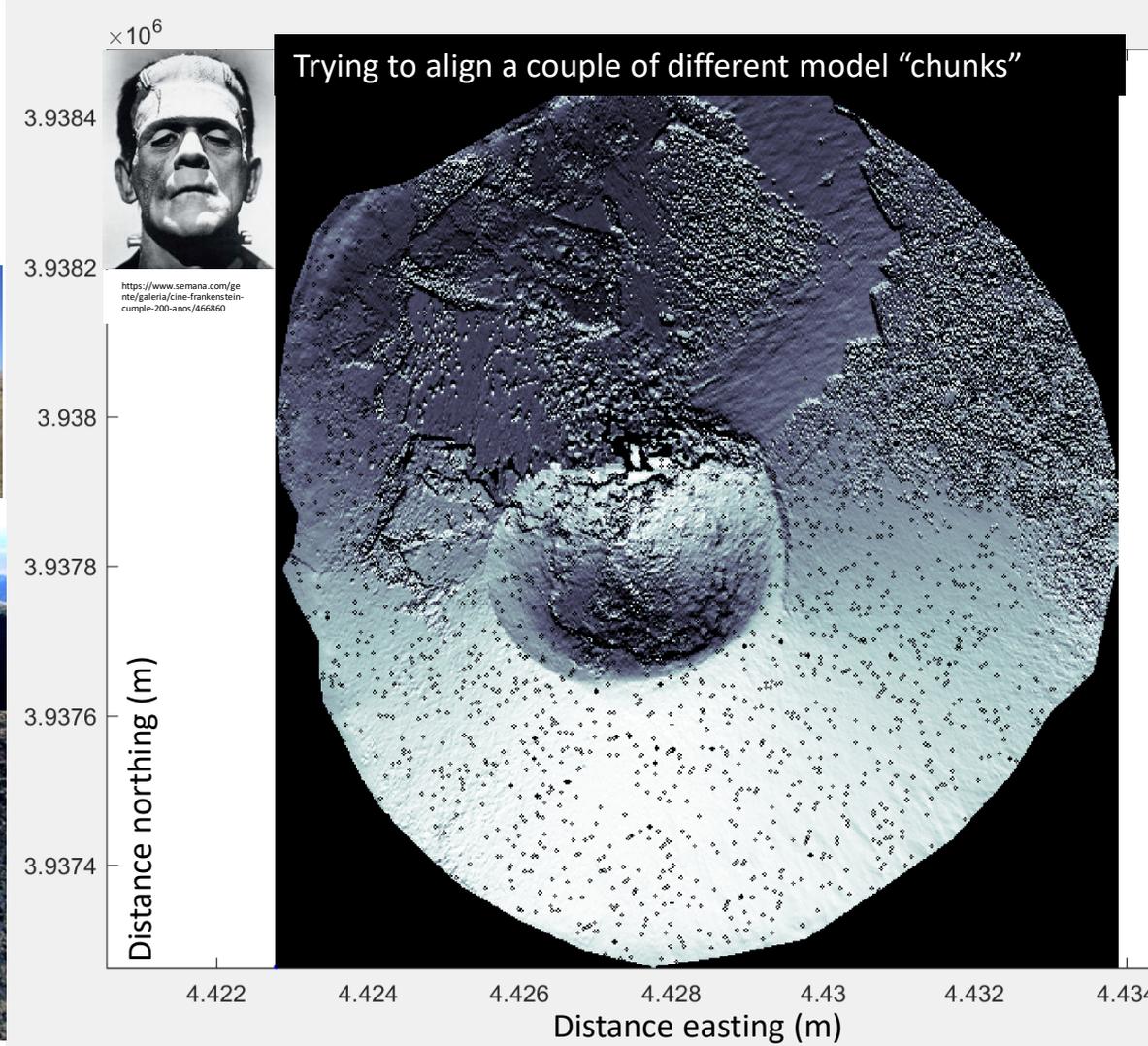
Trying to get at least a few pictures along the Altyn Tagh Fault, western China (1998)

- 16 and 32 sq. ft. Flowform kites
- 1280x960 pixels from radio triggered Olympus 340 digital camera
- geometry not appropriate for traditional photogrammetry; we needed structure from motion



Trying to build a complete model of SP Crater, Northern Arizona with REU students (2013)

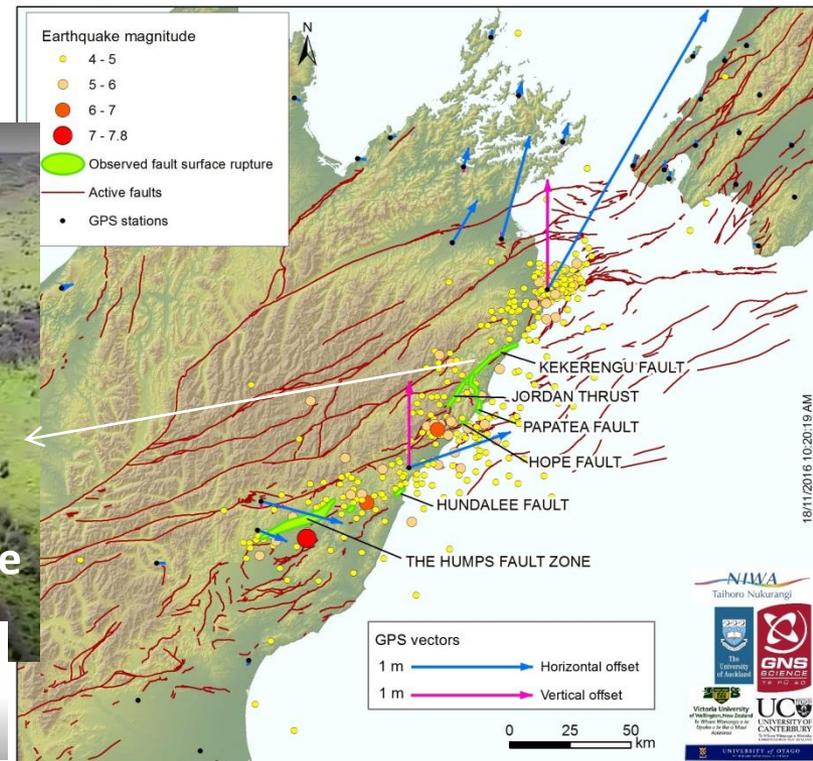
- using balloon and auto kite mounted system
- different surveys, weak ground control, under powered processing machines



Science requirements

- Need topography data with sufficient spatial extent and resolution to capture phenomena of interest
- Need topography data with sufficient temporal repeat to capture changes of interest

Drone video of the Kekerengu Fault rupture



Drone video of the Kekerengu Fault rupture



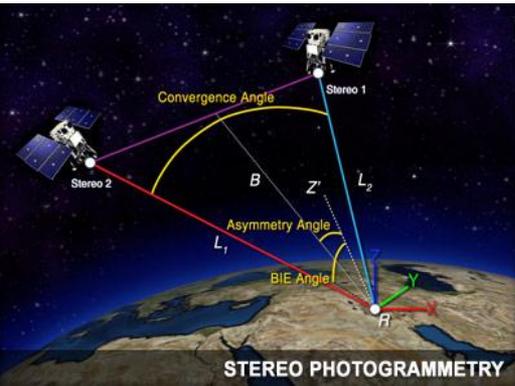
The Kekerengu Fault is one of several faults that ruptured during the Kaikoura Earthquake

Kekerengu alone is 30+ km of this intricate ground rupture

3D IMAGING WITH CAMERAS & LASERS



Space-based



Meters to centimeters spatial sampling

A Airborne LiDAR



onboard GPS and IMU constrain position and orientation of aircraft

distance between scanner and ground return determined from delay between outgoing pulse and reflected return

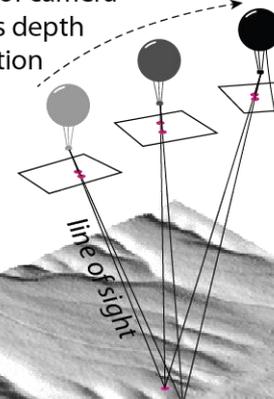
laser pulse

C Structure from Motion

motion of camera provides depth information

sequence of photographs

scene structure refers to both camera positions and orientations and the topography

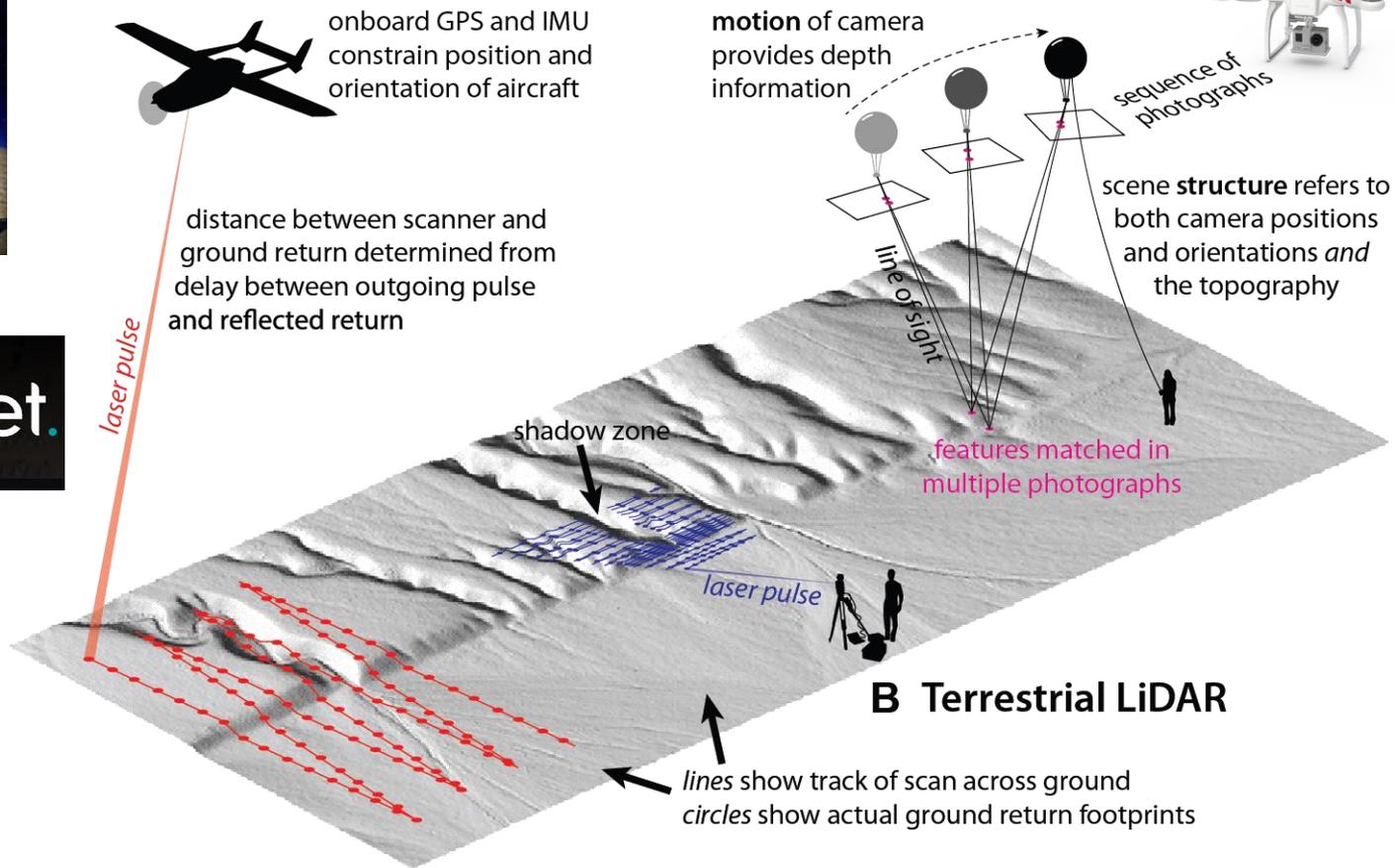


shadow zone

laser pulse

B Terrestrial LiDAR

lines show track of scan across ground
circles show actual ground return footprints



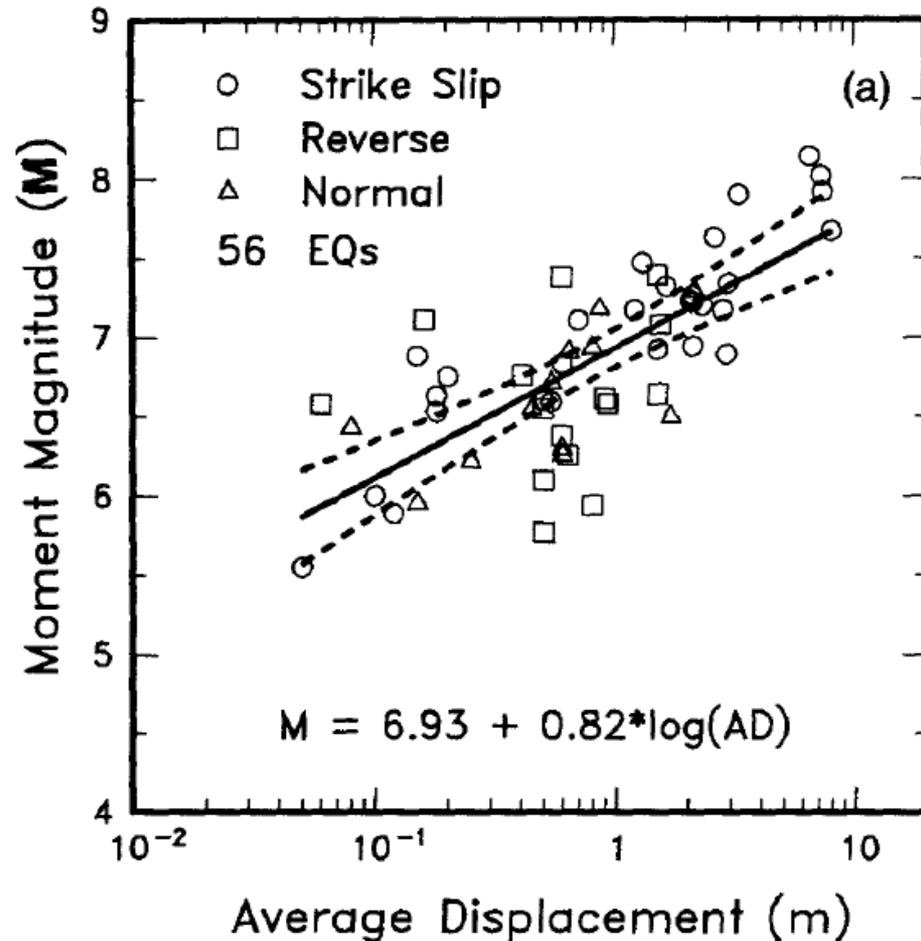
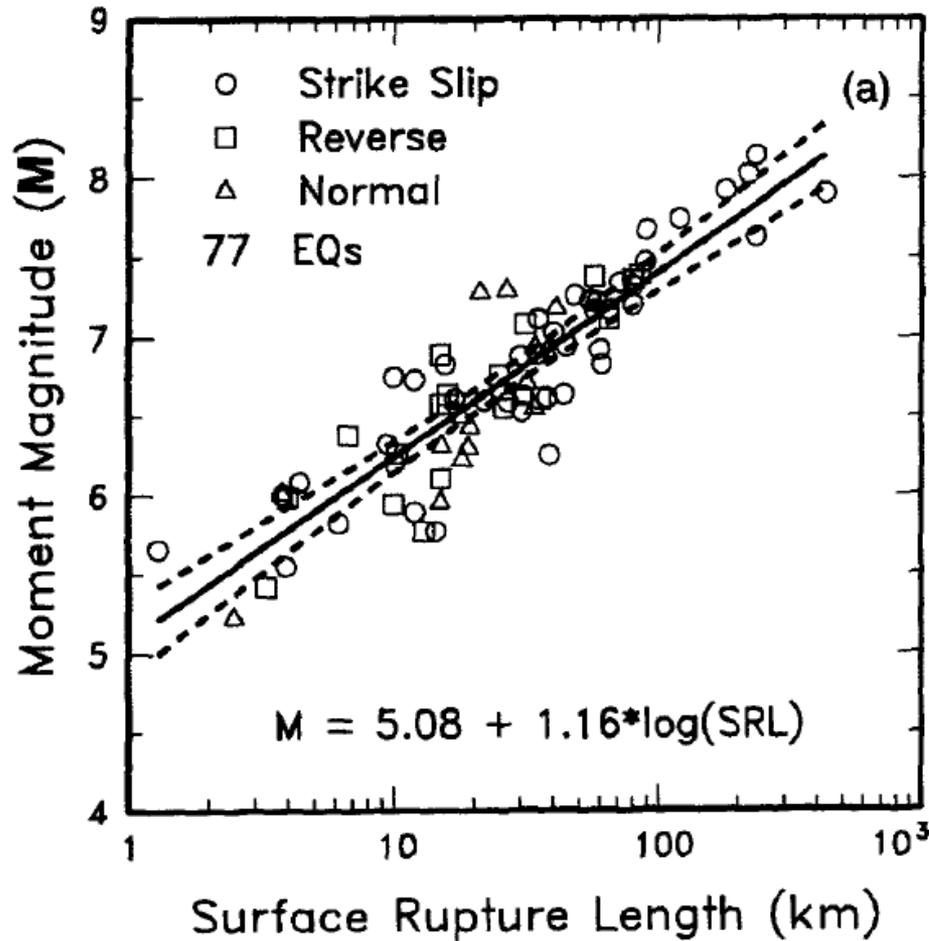
Johnson et al., Geosphere, 2014



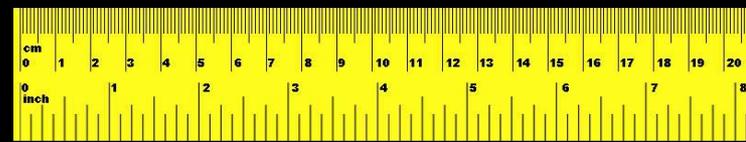
**Need ~<meter-scale sampling to cover critical scale breaks
and temporal repeat to address log(t) response of some phenomena**

Length scales $>10^5\text{m}$ and $<1\text{m}$

Wells and Coppersmith, 1994



“Seeing” at the appropriate scale means measuring at the right scale



Surface processes act to change elevation through erosion and deposition while tectonic processes depress or elevate the surface directly—their record is best characterized with the right fine scale.

Applies in particular to statistical self similarity

How long is the coast of Britain?

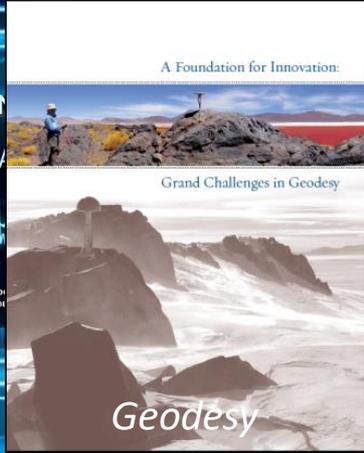
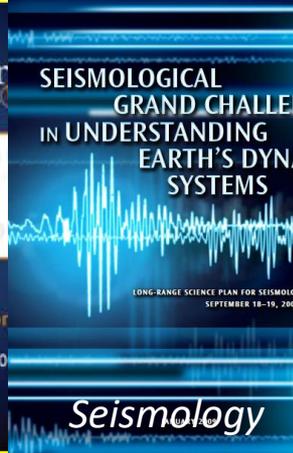
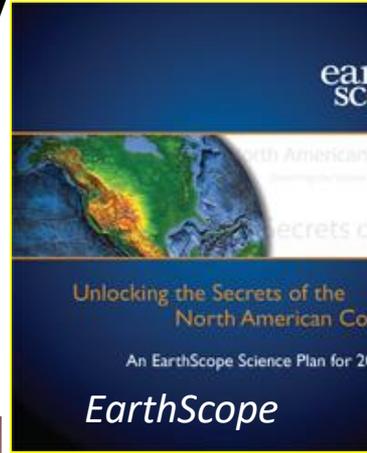
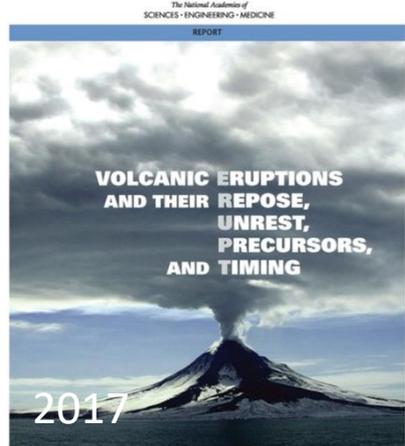
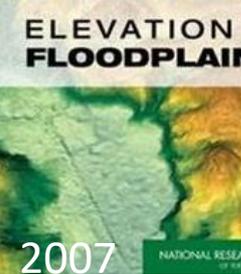
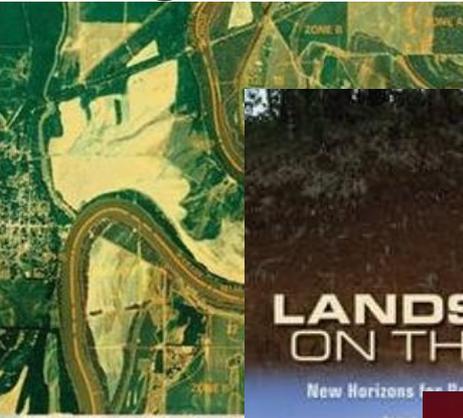
Statistical self-similarity and fractional dimension

Science: 156, 1967, 636-638

B. B. Mandelbrot

Major US community studies recognize the scientific value of high resolution topography

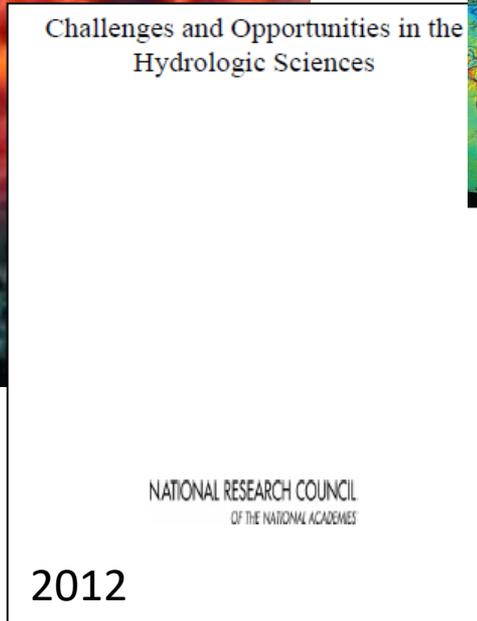
Science communities



2016

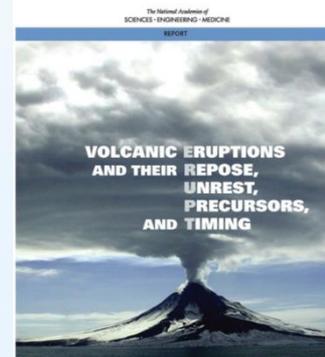
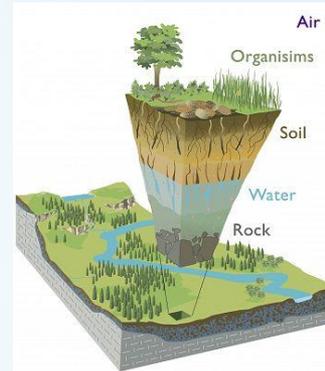
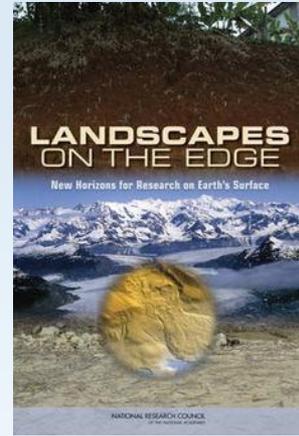


Report from the NASA Earth Surface and Interior (ESI) Focus Area Workshop, November 2-3, 2015, Arlington, Virginia



Example scientific motivations

- How do geopatterns on the Earth's surface arise and what do they tell us about processes?
- How do landscapes influence and record climate and tectonics?
- What are the transport laws that govern the evolution of the Earth's surface?
- How do faults rupture and slip throughout multiple earthquake cycles and what are the implications for earthquake hazard?
- Landscape and ecosystem dynamics
- Volcano form and process
- Changes in volume of domes, edifice, flows



Advances in and decreasing costs for software (algorithms such as structure from motion), computational hardware (rapid computation of colored point clouds and textured 3D models), and unmanned aerial vehicles (UAVs) as semi-autonomous sensing platforms has absolutely changed the geoscientist's toolkit.

Proc. R. Soc. Lond. B. **203**, 405–426 (1979)
Printed in Great Britain

The interpretation of structure from motion

BY S. ULLMAN

*Artificial Intelligence Laboratory, Massachusetts Institute of Technology,
545 Technology Square (Room 808), Cambridge, Massachusetts 02139 U.S.A.*

(Communicated by S. Brenner, F.R.S. – Received 20 April 1978)

The interpretation of structure from motion is examined from a computational point of view. The question addressed is how the three dimensional structure and motion of objects can be inferred from the two dimensional transformations of their projected images when no three dimensional information is conveyed by the individual projections.

*Proc. of the International Conference on
Computer Vision, Corfu (Sept. 1999)*

Object Recognition from Local Scale-Invariant Features

David G. Lowe

Computer Science Department
University of British Columbia
Vancouver, B.C., V6T 1Z4, Canada
lowe@cs.ubc.ca

Abstract

An object recognition system has been developed that uses a new class of local image features. The features are invariant to image scaling, translation, and rotation, and partially invariant to illumination changes and affine or 3D projection.

Software

Freely available

Bundler Photogrammetry Package^{a,b}
SFMToolkit^{a,b}
Python Photogrammetry Toolbox (PPT)^{a,b}
VisualSFM^b

3DF Samantha

Web sites and services

Photosynth

Arc3D
CMP SfM Web service^a
Autodesk 123D Catch
Pix4D
My3DScanner
Commercial
PhotoScan
Acute3D
PhotoModeler

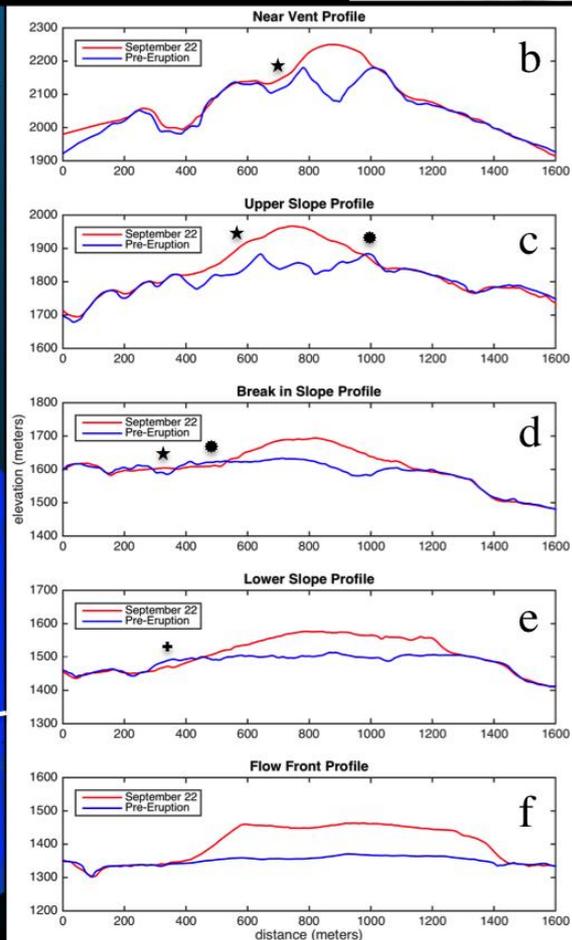
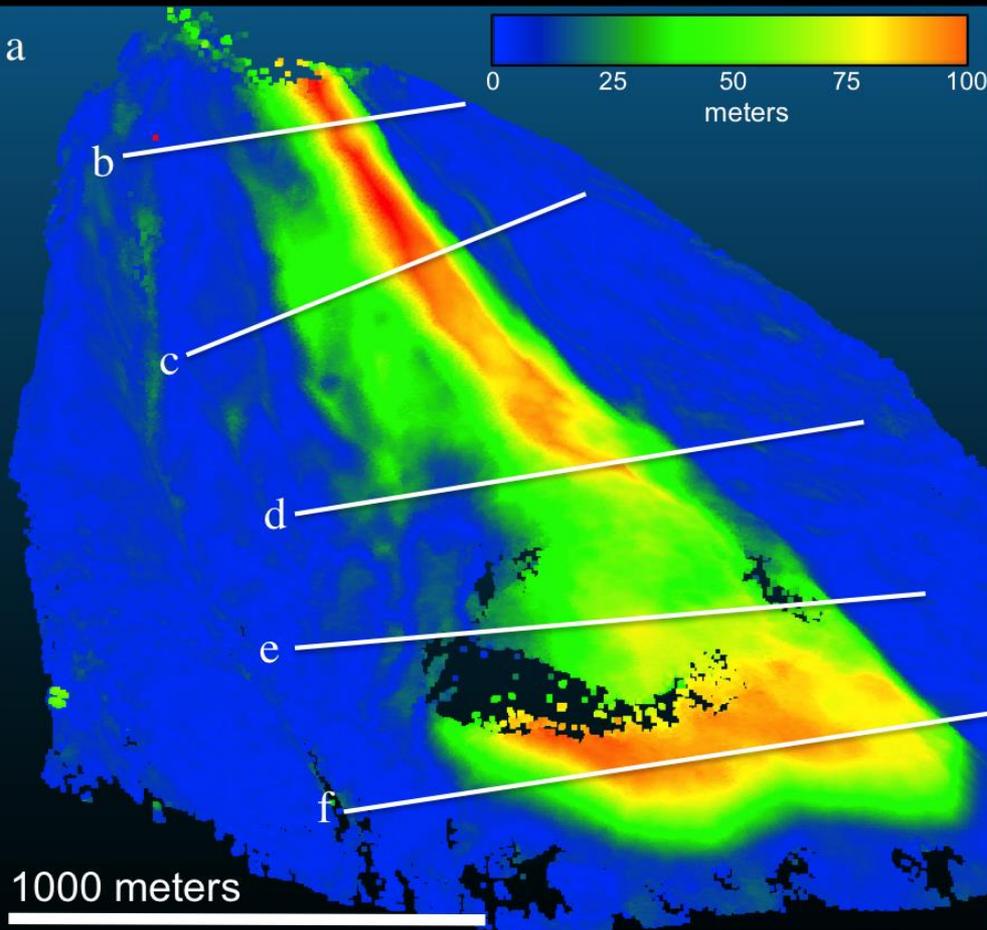
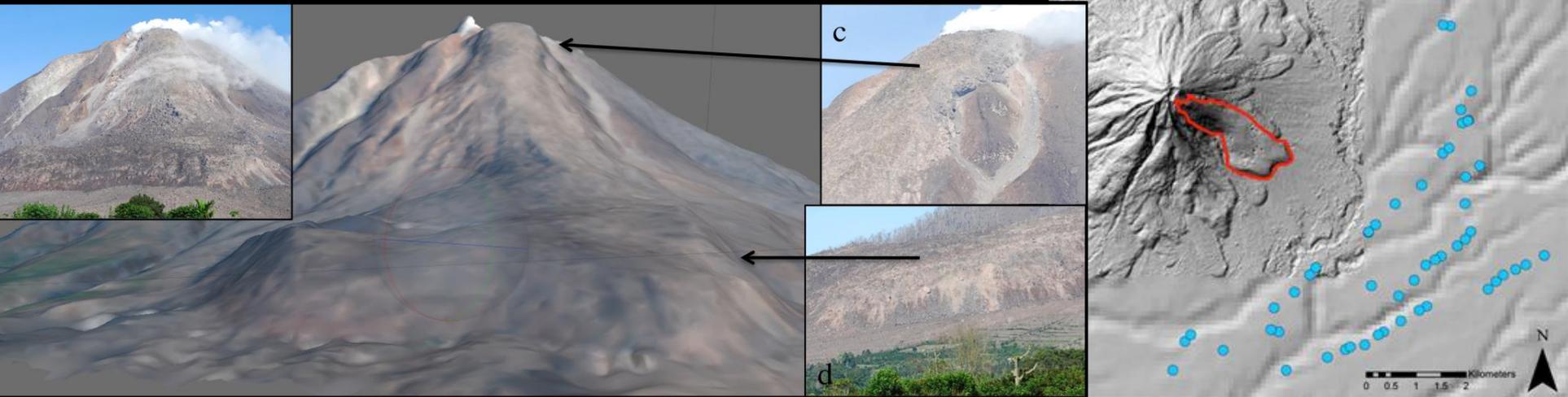
3DF Zephyr Pro

Bemis, et al., 2014

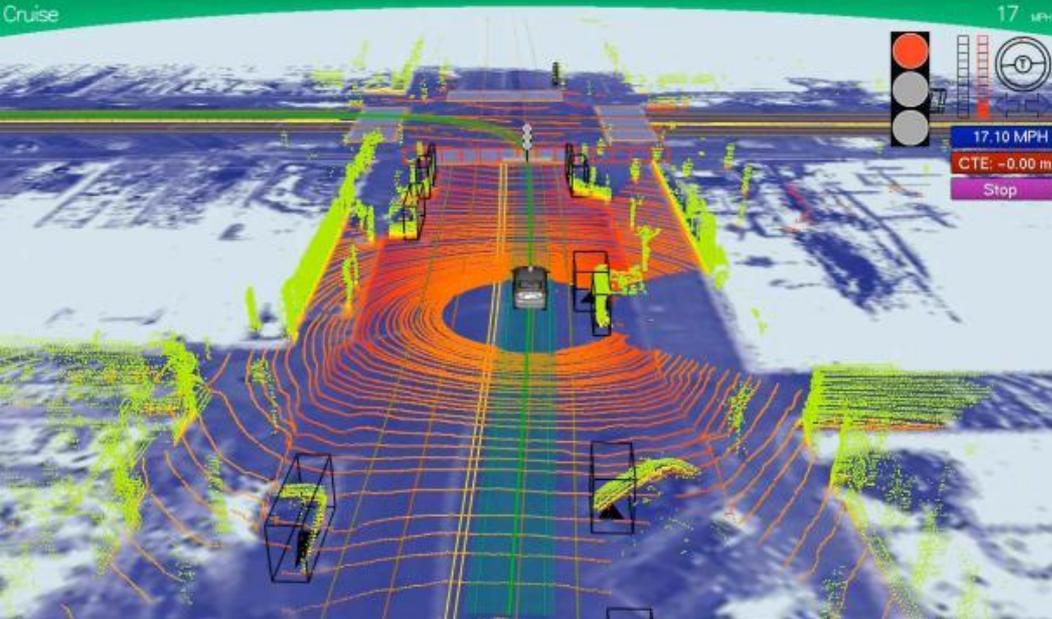


<https://www.dell.com/en-us/gaming/alienware-desktops>





The emplacement of the active lava flow at Sinabung Volcano, Sumatra, Indonesia, documented by structure-from-motion photogrammetry -Carr, et al., 2018. Pre-eruption 5 m DEM and post eruption SfM registered to unchanged areas



*Google car:
Gb/sec high
accuracy
navigation data*



*Modeling the World from Internet Photo
Collections (Snavely, et al., Int J Comput
Vis, 2007)*

Ubiquitous point clouds + 3D models: coordinated (mapping and monitoring) and haphazard (autonomous navigation, individual photo collections, etc.)
-Need open access and cyberinfrastructure to support archive, and rapid query, data handling, preprocessing, and differencing