

# Introduction to Terrestrial Laser Scanning for Earth Science Research and Education

Christopher Crosby & Marianne Okal (UNAVCO)

*2017 GSA Short Course, Seattle, WA*



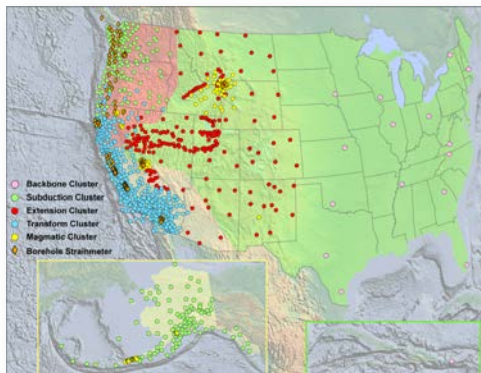


**UNAVCO** is a non-profit, membership governed consortium of universities that facilitates geoscience research and education using geodesy.

**UNAVCO** supports GPS, borehole geophysics, InSAR, and lidar data acquisition, data archiving, equipment, development & testing, training.

**UNAVCO** operates and maintains the **Plate Boundary Observatory** network of instruments.

**UNAVCO Education & Community Engagement** works to promote a broader understanding of Earth science.



**Video...**

<https://www.youtube.com/watch?v=yxLMk120vMU>



# GEODETIC IMAGING AT UNAVCO

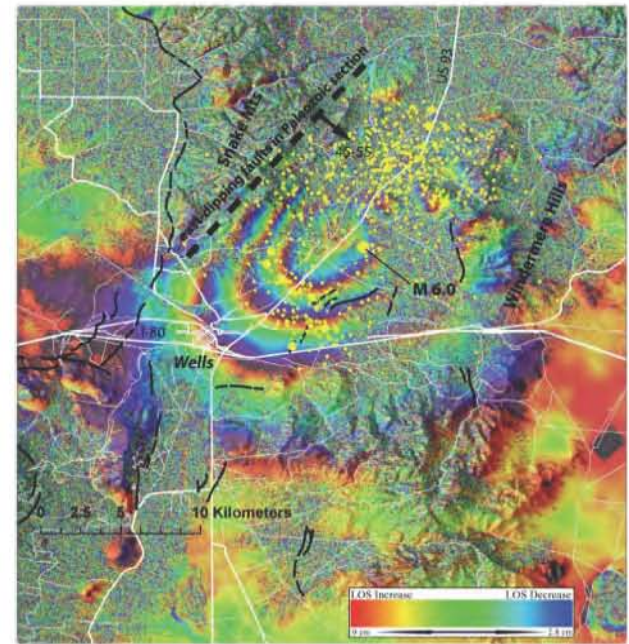
UNAVCO



Terrestrial LiDAR



Airborne/  
Spaceborne  
InSAR



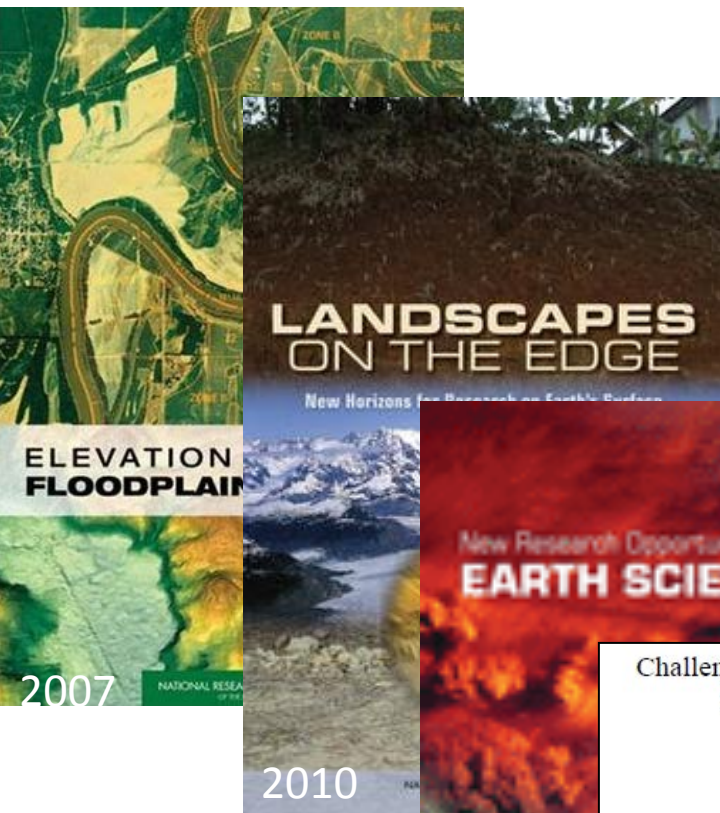
Airborne/  
Spaceborne LiDAR



Terrestrial Radar



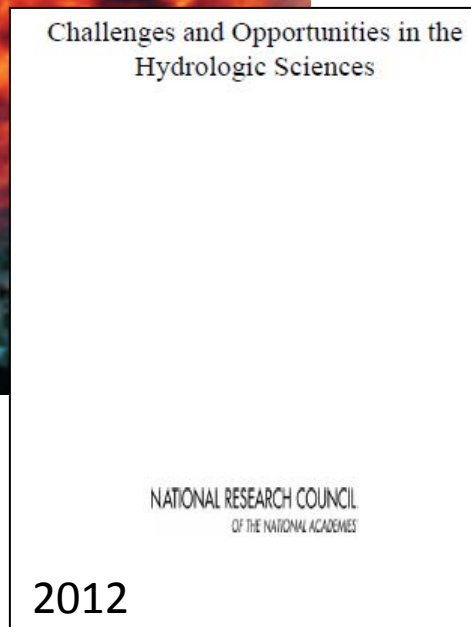
# THE SCIENTIFIC VALUE OF HIGH RESOLUTION TOPOGRAPHY



National Research Council  
sponsored



NSF communities

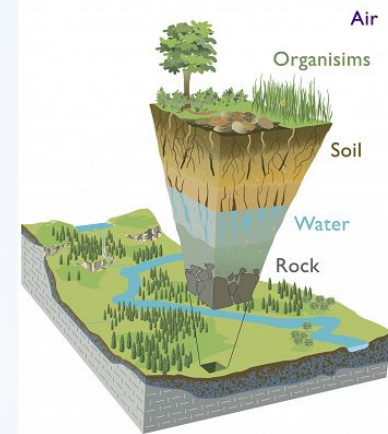
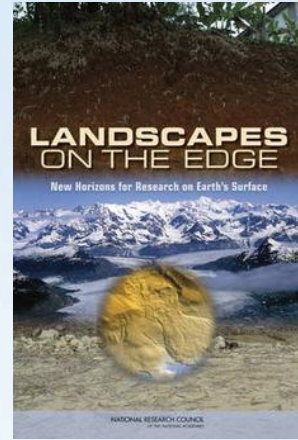


USGS sponsored



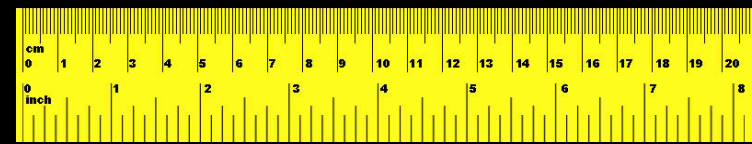
# EXAMPLE SCIENTIFIC MOTIVATIONS

- How do geopatterns on the Earth's surface arise and what do they tell us about processes?
- How do landscapes influence and record climate and tectonics?
- What are the transport laws that govern the evolution of the Earth's surface?
- Coupled hydrogeomorphic-ecosystem response to natural and anthropogenic change
- Landscape and ecosystem dynamics
- Volcano form and process
- Changes in volume of domes, edifice, flows over time





“Seeing” at the appropriate scale  
means measuring at the right scale



*Surface processes act to change elevation through erosion and deposition while tectonic processes depress or elevate the surface directly—their record is best characterized with the right fine scale.*

Applies in particular to statistical self similarity

**How long is the coast of Britain?**

**Statistical self-similarity and fractional dimension**

Science: 156, 1967, 636-638

B. B. Mandelbrot

# GETTING THE RIGHT COVERAGE IN TIME, SPACE, AND RESOLUTION FOR THE QUESTION

Global and regional topography/bathy (10s-100s m/pix)

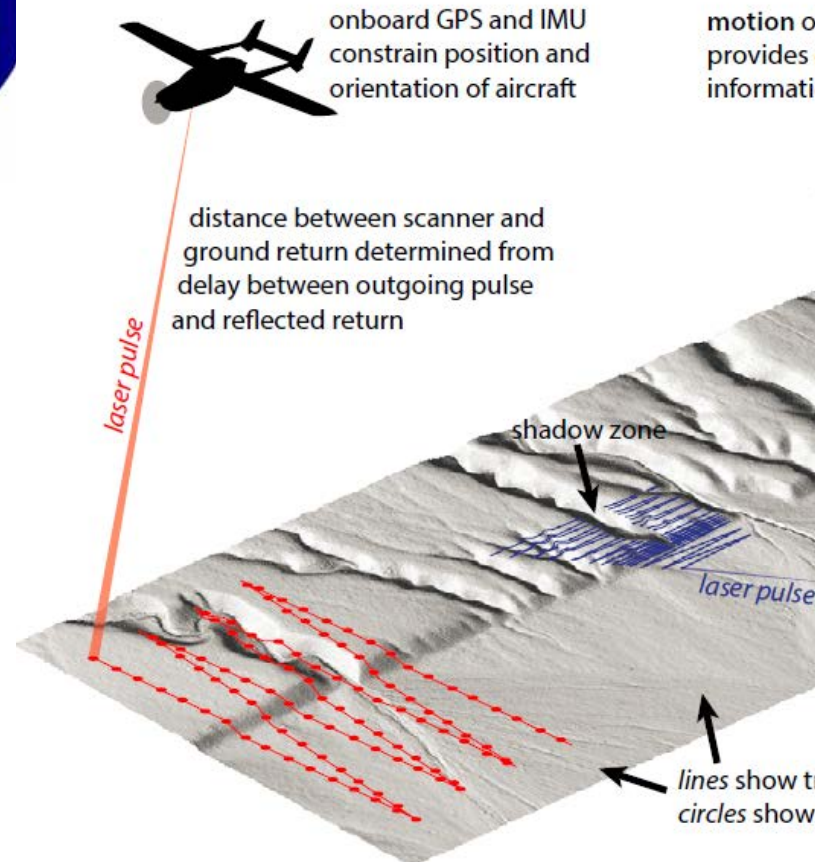


+ASTER, ALOS, etc

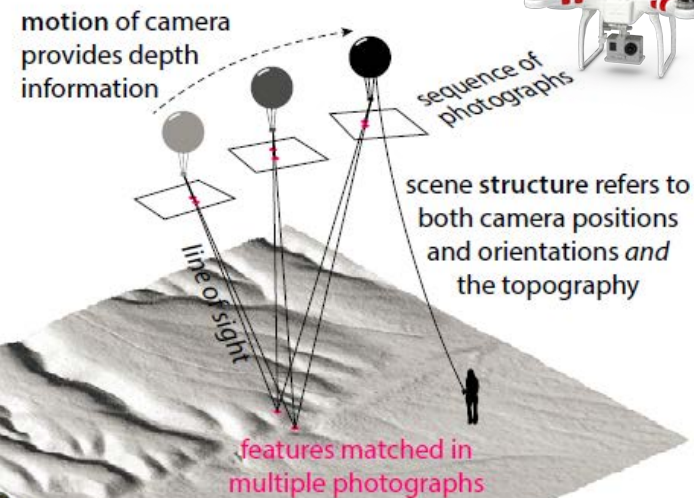


Local to site scale topography (dm to m / pix)

## A Airborne LiDAR



## C Structure from Motion



## B Terrestrial LiDAR

lines show track of scan across ground  
circles show actual ground return footprints

Johnson, K., Nissen, E., Saripalli, S., Arrowsmith, J R., McGarey, P., Scharer, K., Williams, P., Blisniuk, K., Rapid mapping of ultra-fine fault zone topography with Structure from Motion, Geosphere, v. 10; no. 5; p. 1–18; doi:10.1130/GES01017.1, 2014.



## Support Resources

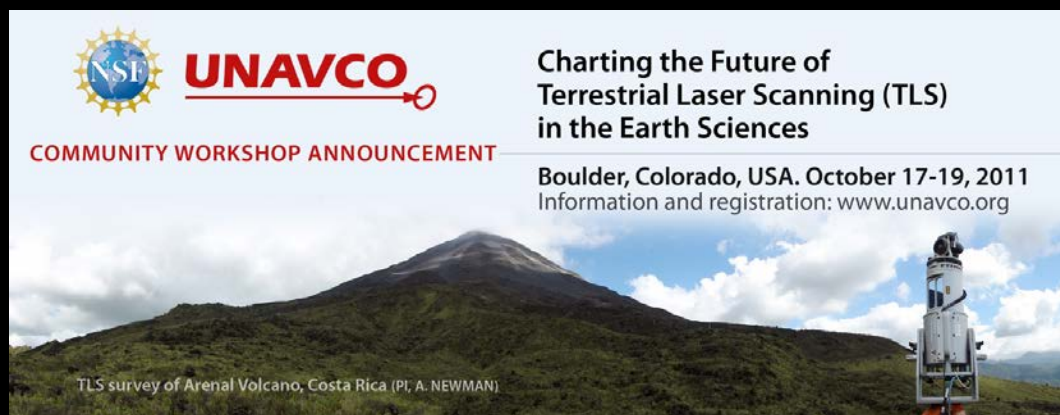
- Instrumentation
- Field engineering
- Data processing
- Training
- Data archiving & dissemination

## Community Building

- Workshops
- Inter-Agency collaborations & partnerships

## Education and Outreach

- Training courses
- Field courses



GSA 2012 UNAVCO TLS short course, Charlotte, NC

## Scanners funded by the National Science Foundation



**Riegl VZ-2000**



**Riegl VZ-1000**



**Riegl VZ-400**



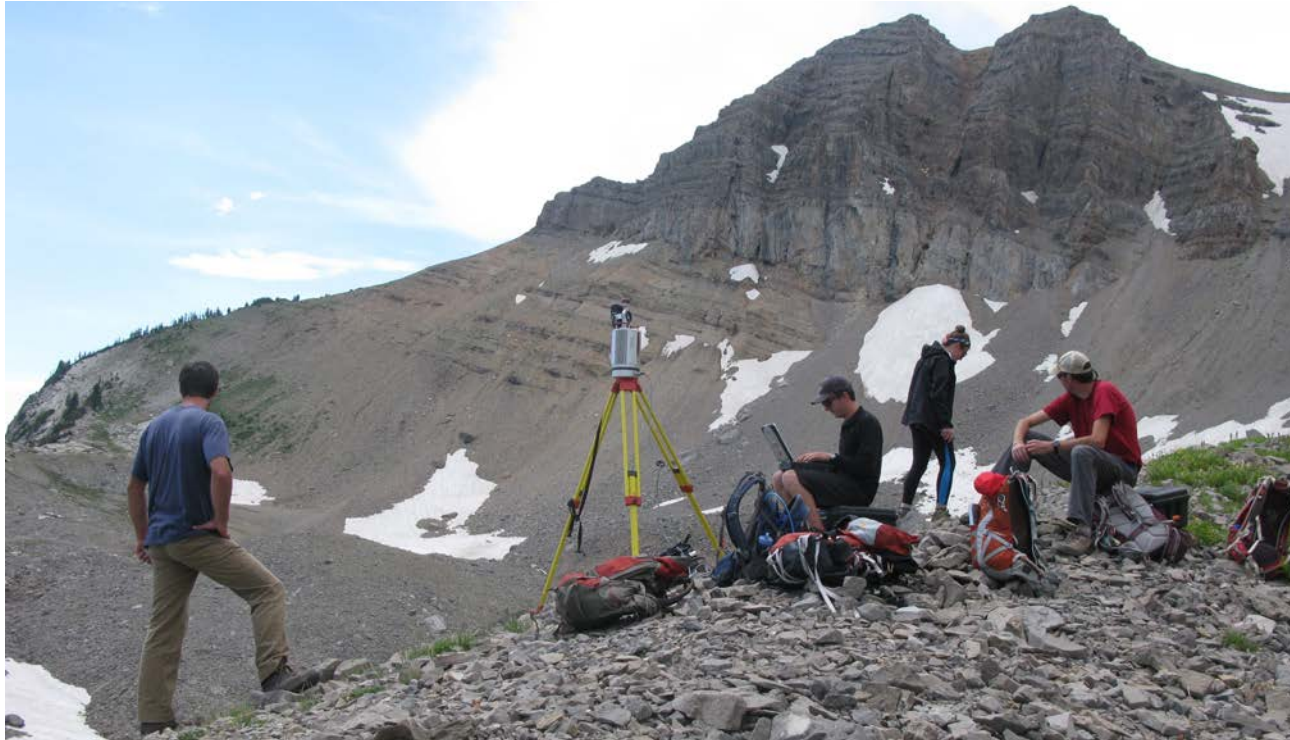
**Riegl Z620**



**Leica C10**

Laser wavelength	Near infrared				532 nm (green)
Effective range	2050 m	1400 m	500 m	2000 m	150 m
High-speed meas. rate	396,000 pts/sec	122,000 pts/sec	125000 pts/sec	11,000 pts/sec	50,000 pts//sec
Precision	5 mm	5 mm	5 mm	10 mm	4 mm
Accuracy	8 mm	8 mm	5 mm	10 mm	6 mm
Field of view	100°x 360°	100°x 360°	100°x 360°	80°x 360°	270°x 360°
Dimensions	308 mm x 196 mm	308 mm x 180 mm	308 mm x 180 mm	463 mm x 210 mm	238 mm x 395 mm
Weight	9.9 kg	9.8 kg	9.8 kg	16 kg	13 kg





- Campaign and RTK GPS, tripods, various power supply options
- Instrument validation range
- License server with access to RiScan Pro, Cyclone, Polyworks, ArcGIS, Blue Marble Geographic Calculator,

## *Light Detection and Ranging (lidar)*

- Accurate distance measurements with a laser rangefinder
- Distance is calculated by measuring the two-way travel time of a laser pulse.
- Near IR (1550nm) or green (532nm)

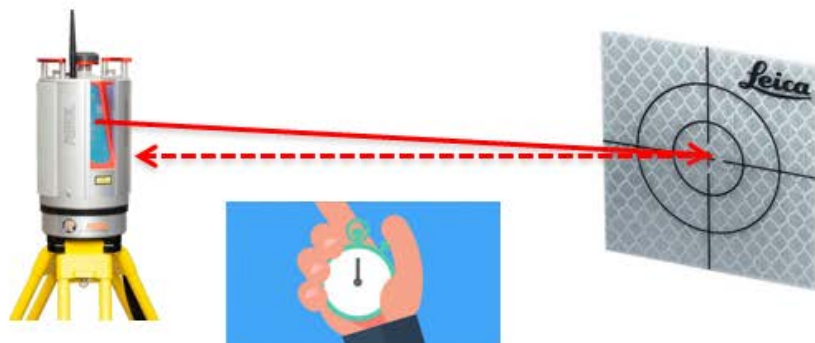




## Time of flight

Time it takes for emitted pulse to reflect off object and return to scanner.

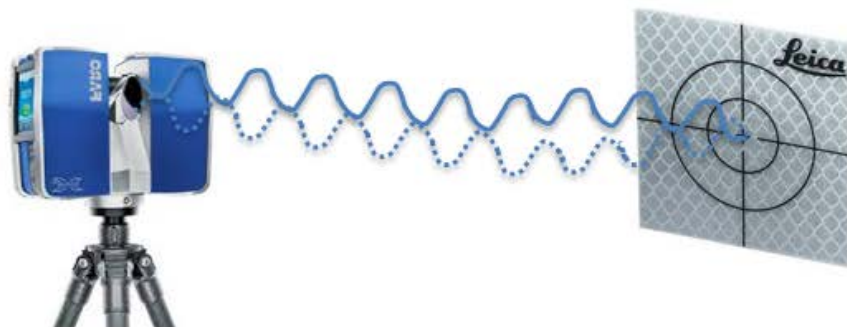
$$\text{Distance} = \frac{\text{Speed of Light} \times \text{Time of Flight}}{2}$$



## Phase Shift

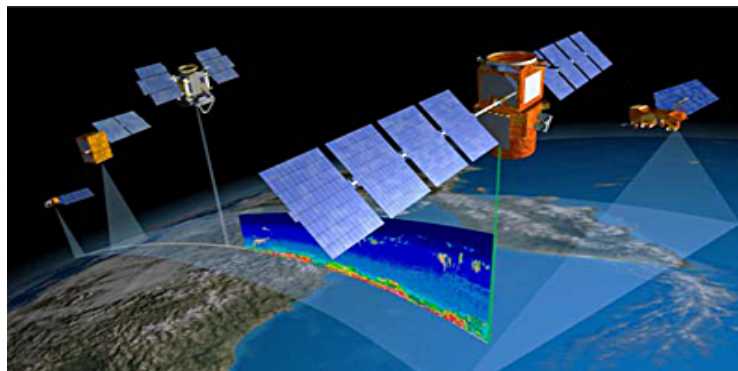
Distance is calculated along a sinusoidally modulated laser pulse.

$$\text{Time of Flight} = \frac{\text{Phase Shift}}{2\pi \times \text{Modulation Frequency}}$$





BUSINESS WIRE COMMERCIAL PHOTO



J. Stoker,  
USGS



*Similar technology, different platforms:*

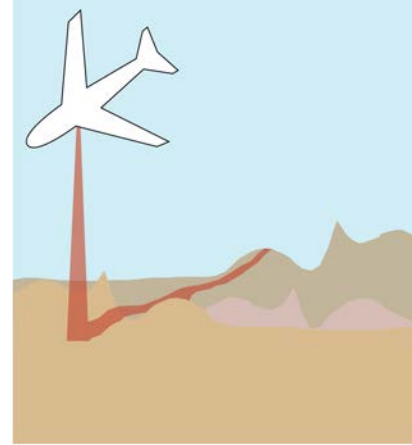
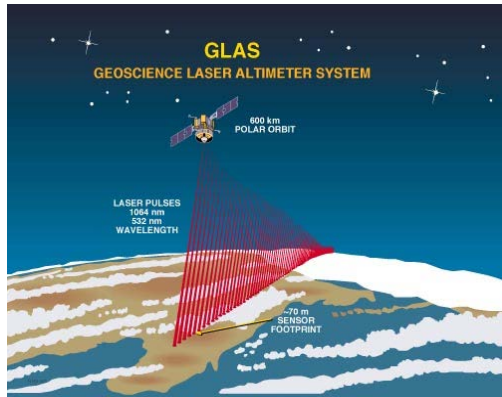
## Terrestrial Laser Scanning (TLS)

- Also called ground based lidar or T-lidar.

Laser scanning moving ground based platform = Mobile Laser Scanning (MLS).

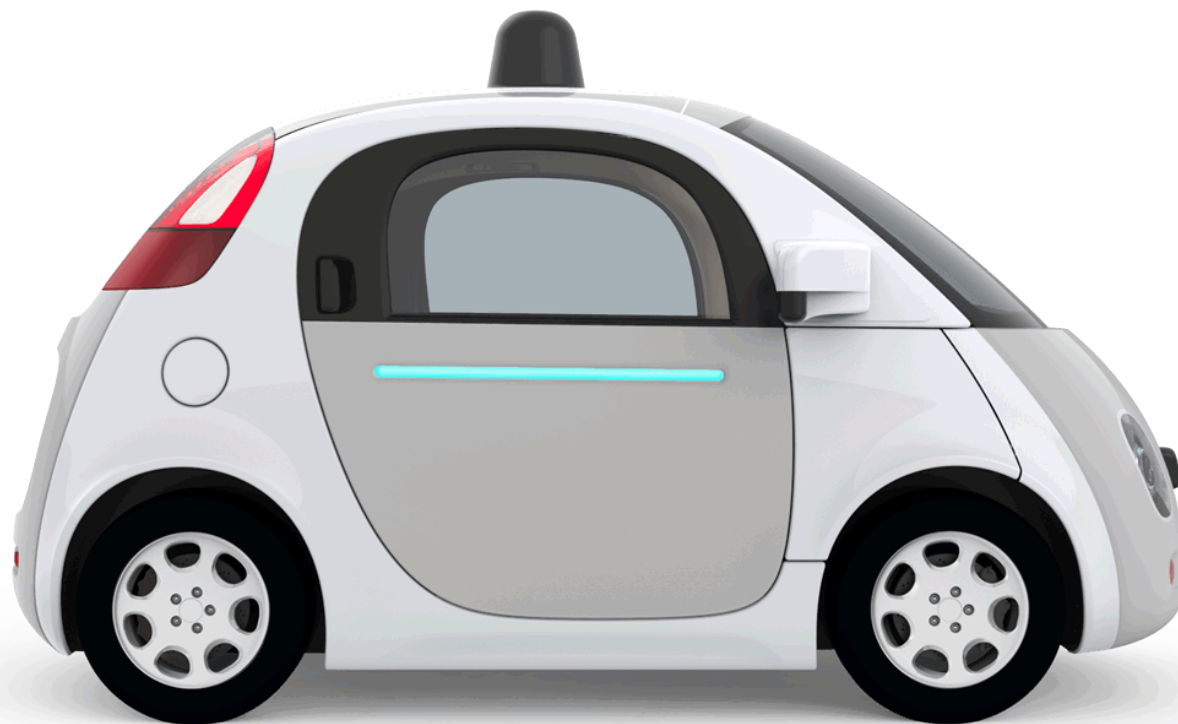
Laser scanning from airborne platform = Airborne Laser Scanning (ALS).





System:	Spaceborne (e.g. GLAS)	High Altitude (e.g. LVIS)	Airborne (ALS)	Terrestrial (TLS)
Altitude:	600 km	10 km	1 km	1 m
Footprint:	60 m	15 m	25 cm	1–10 cm
Vertical Accuracy	15cm to 10m depends on slope	50/100 cm bare ground/ vegetation	20 cm	1–10 cm Depends on range, which is few meters to 2 km or more

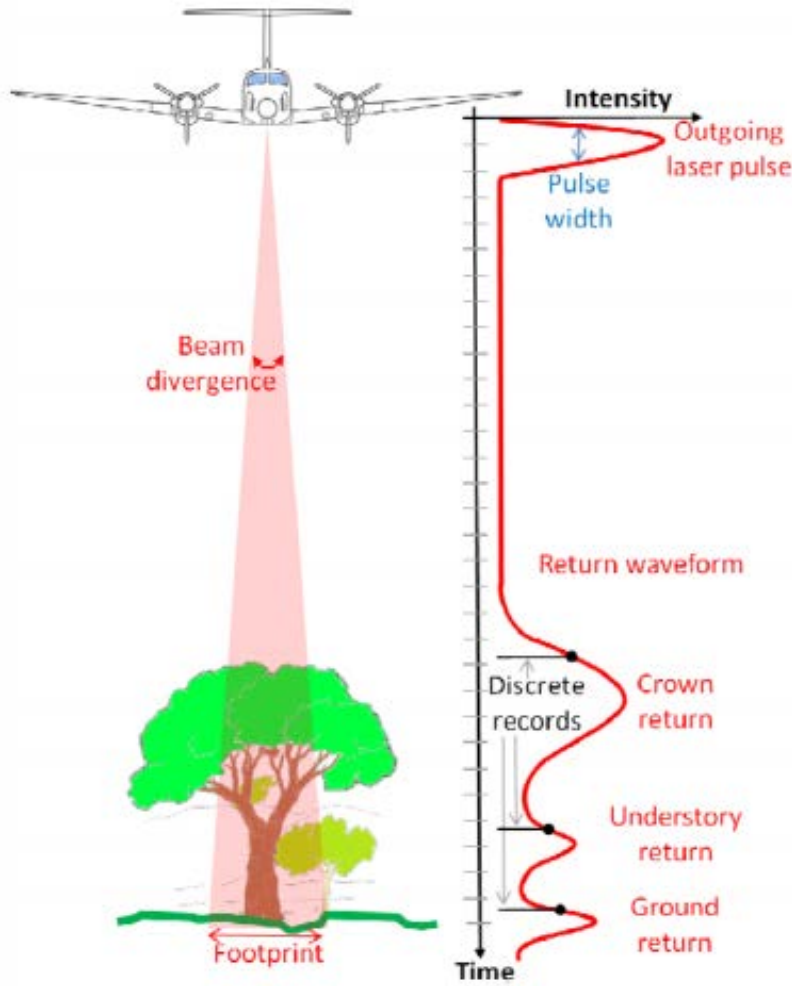
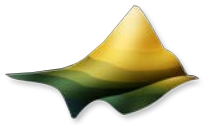








# DISCRETE PULSE AND FULL WAVEFORM LIDAR

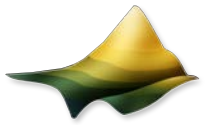


Discrete pulse = binary yes or no return. Only location of return is saved.

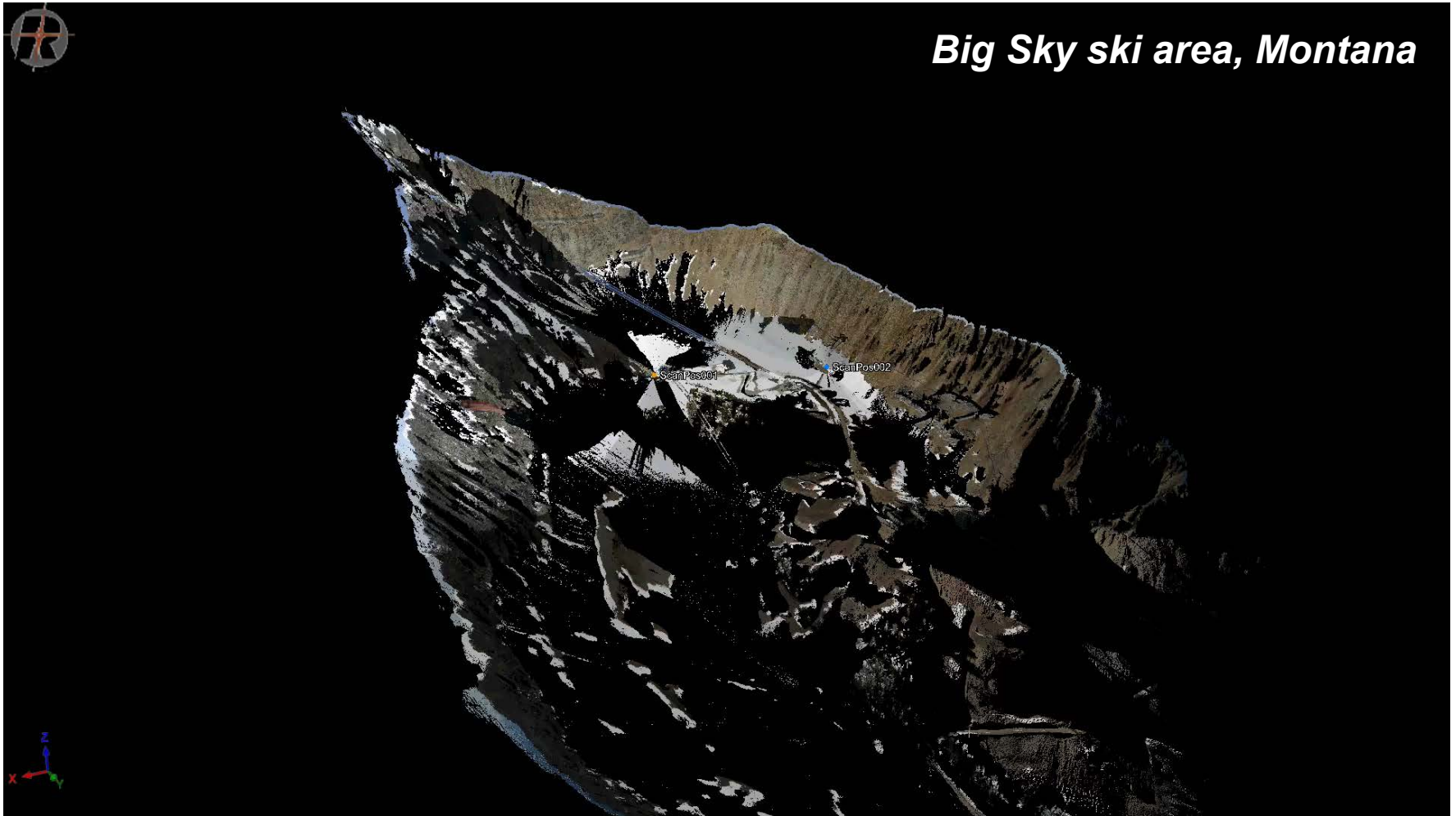
Full waveform = digitized backscatter waveform. Saves the full return energy signature

Data size / processing time vs. enhanced information

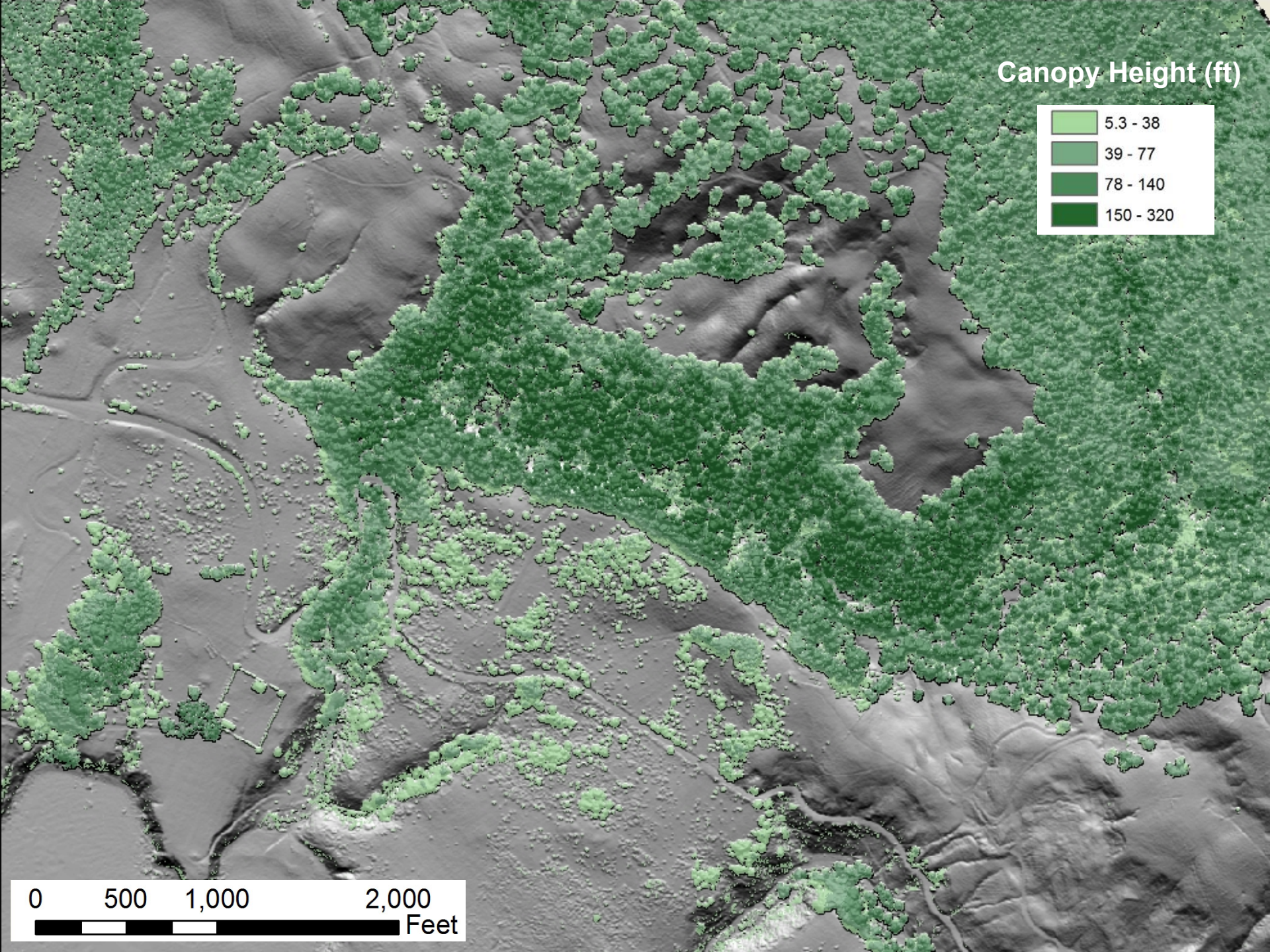
# LIDAR DATA DELIVERABLES



A ***point cloud*** is the fundamental lidar dataset – discrete x,y,z points with attributes (Intensity, return number & number of returns, classification, gps time, RGB...):



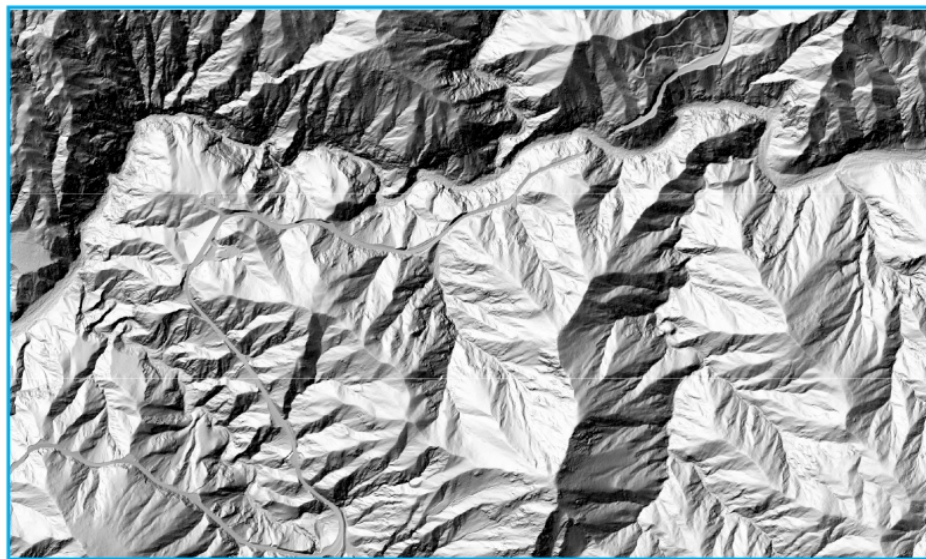




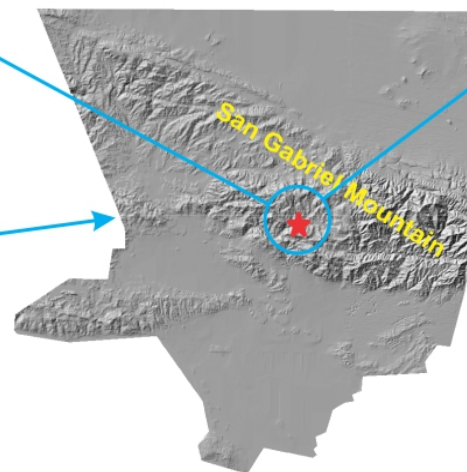




California



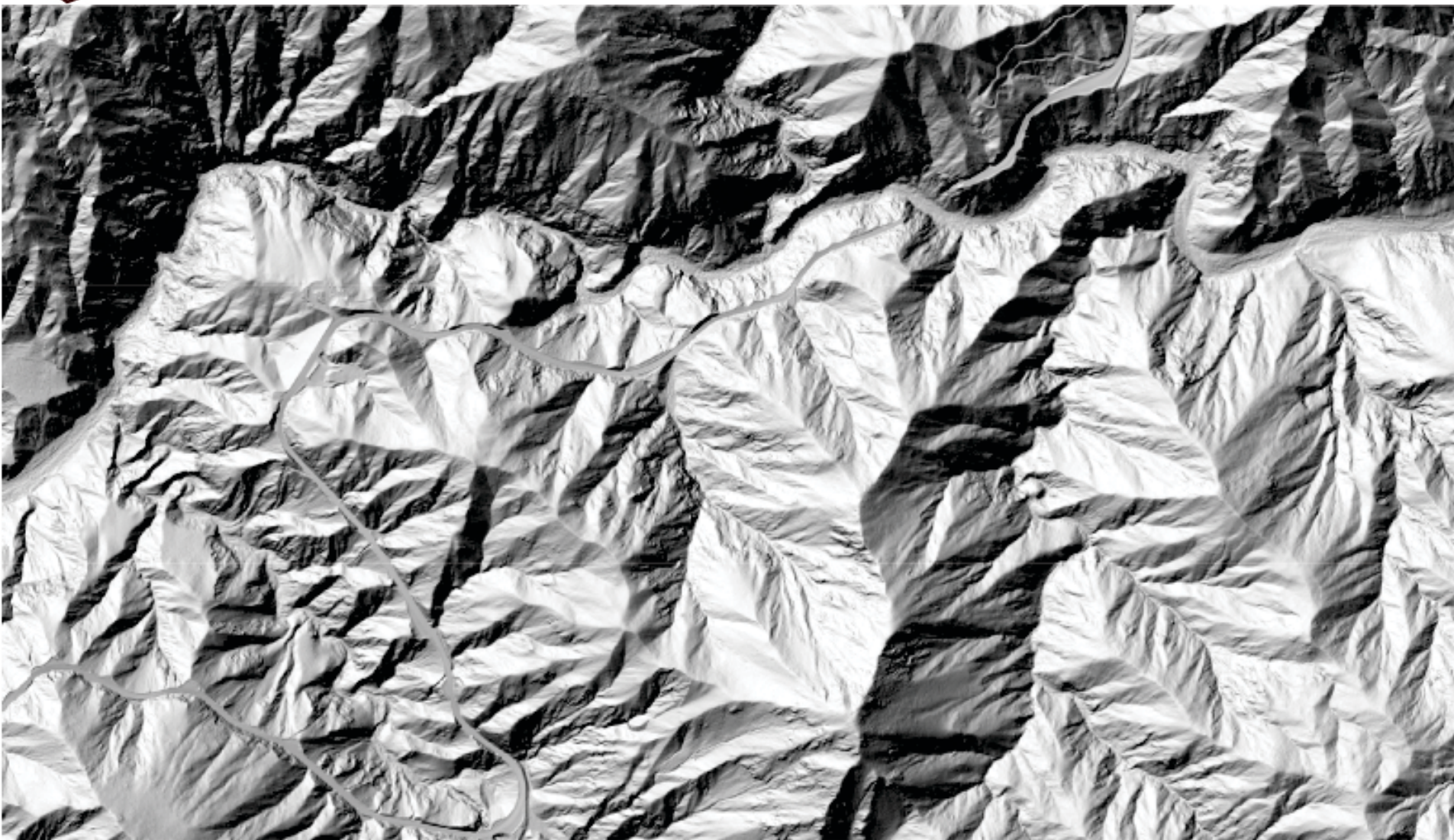
Study Area



Los Angeles County





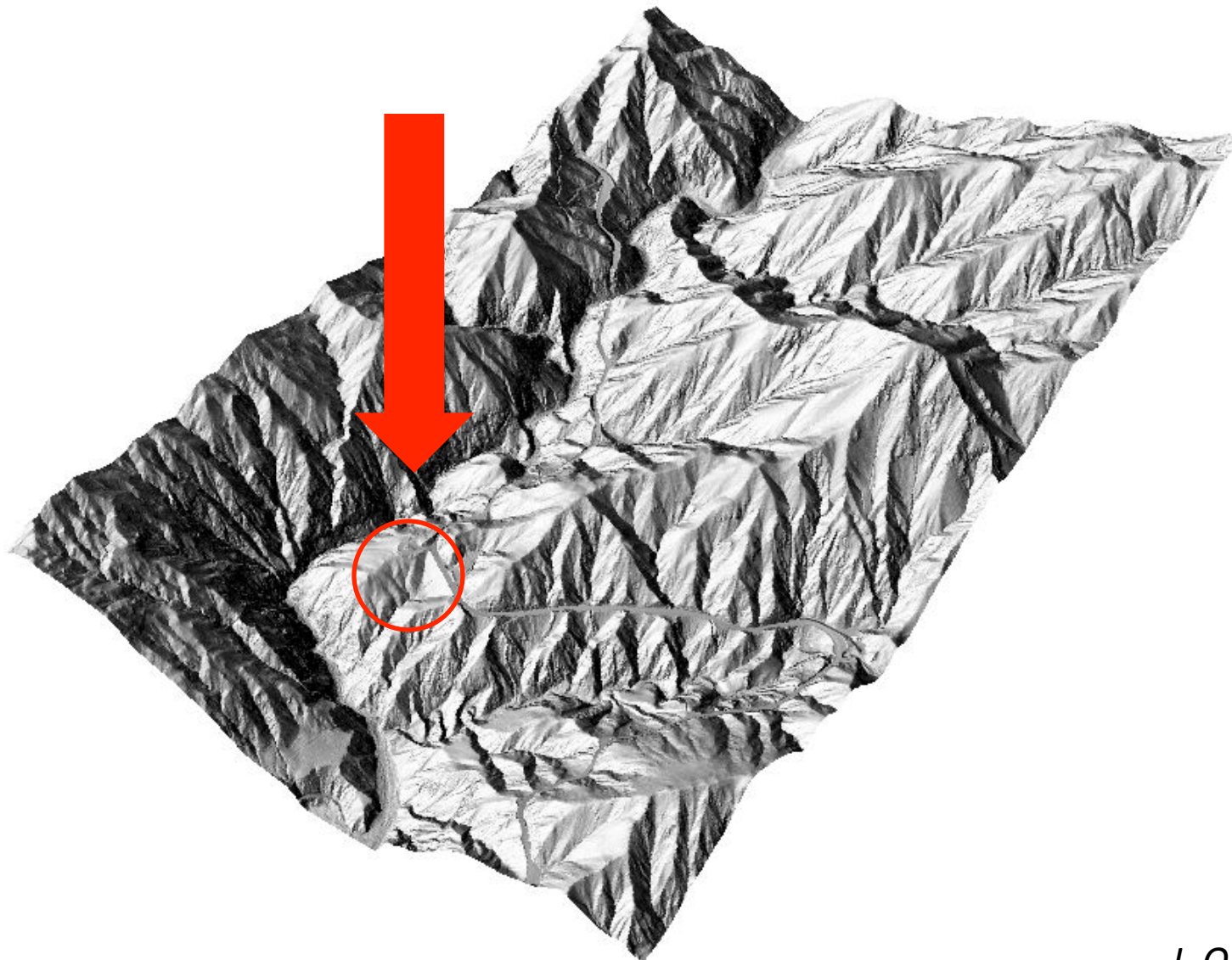


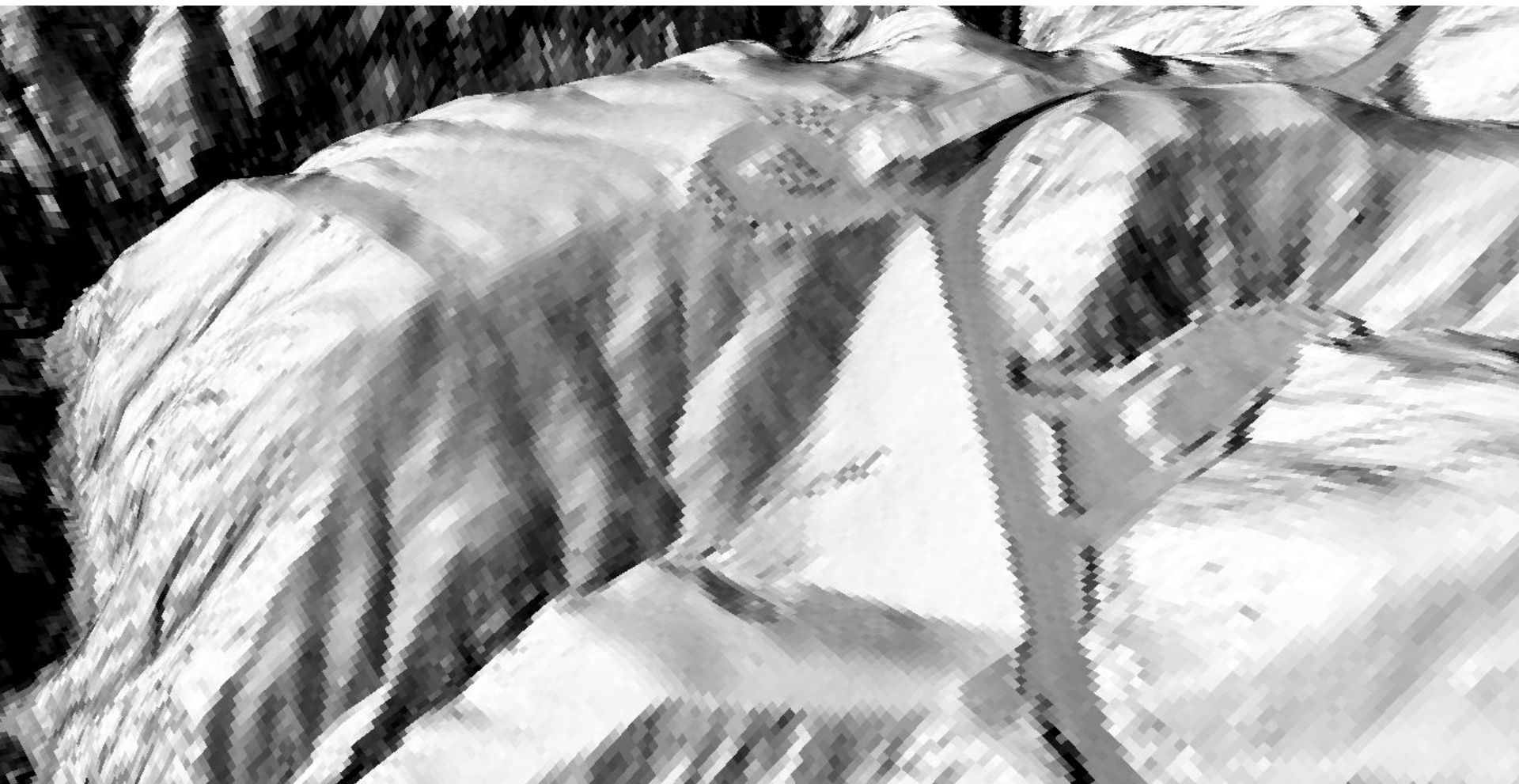
San Gabriel Mountain 1-m DEM from airborne lidar



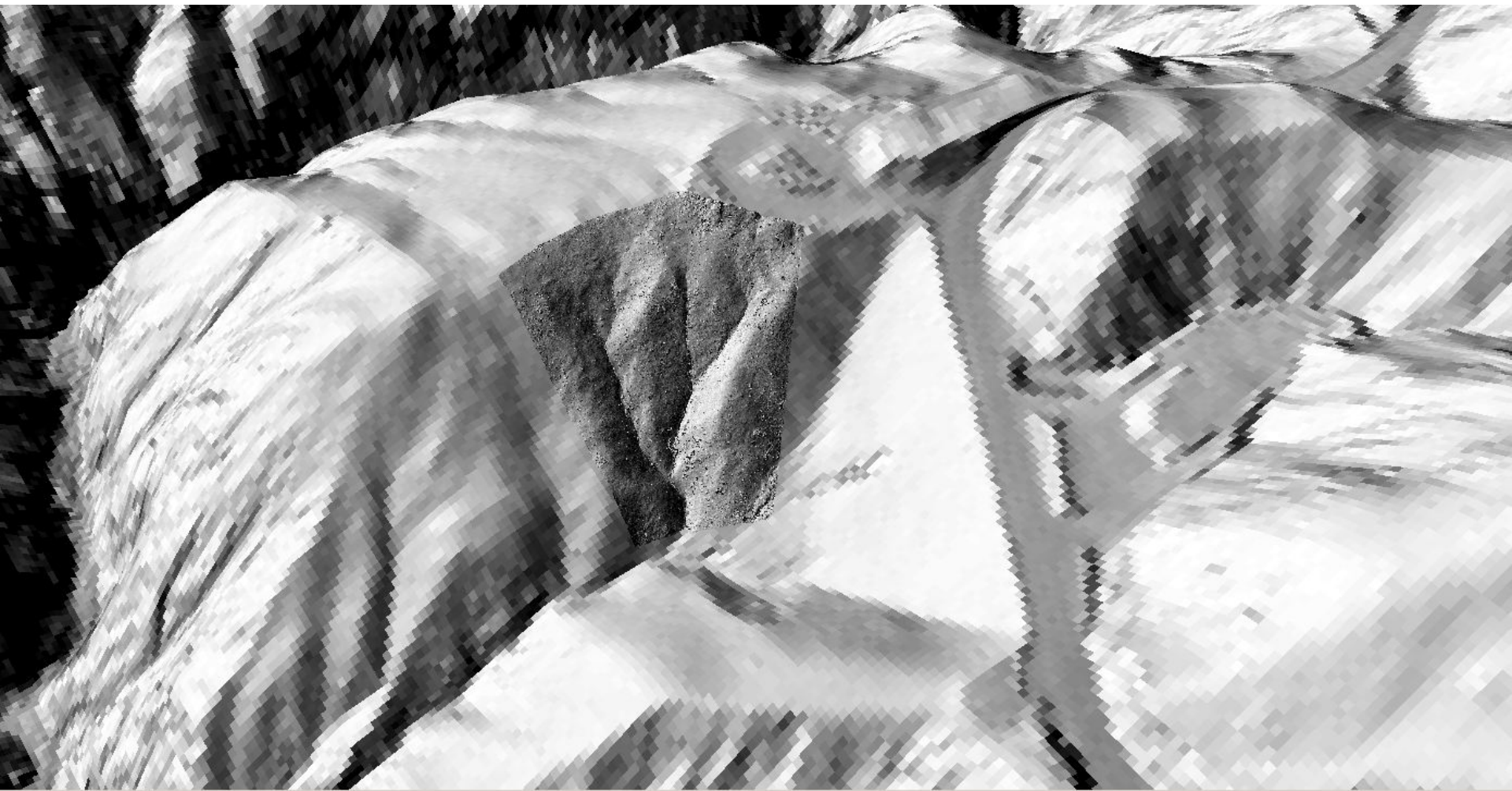






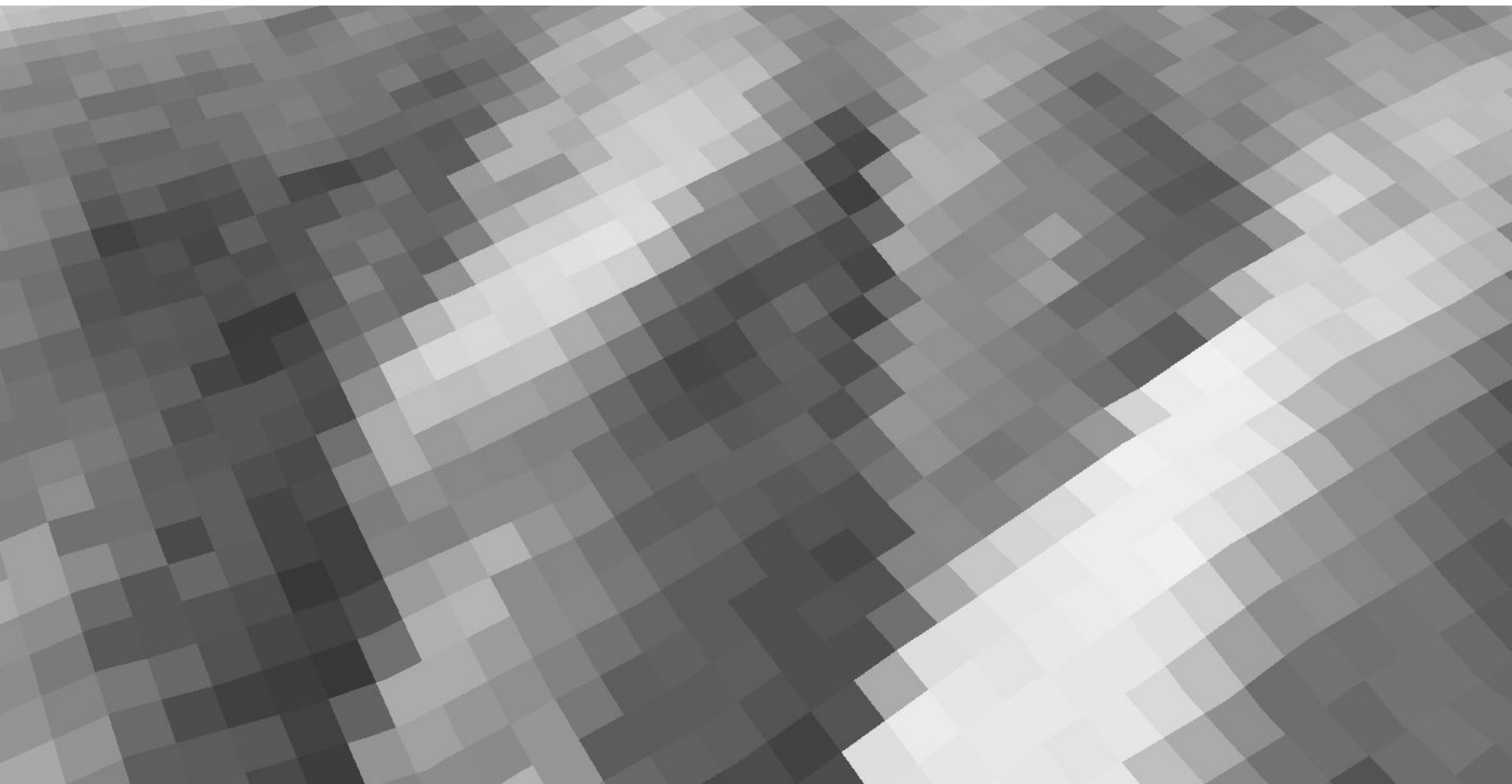


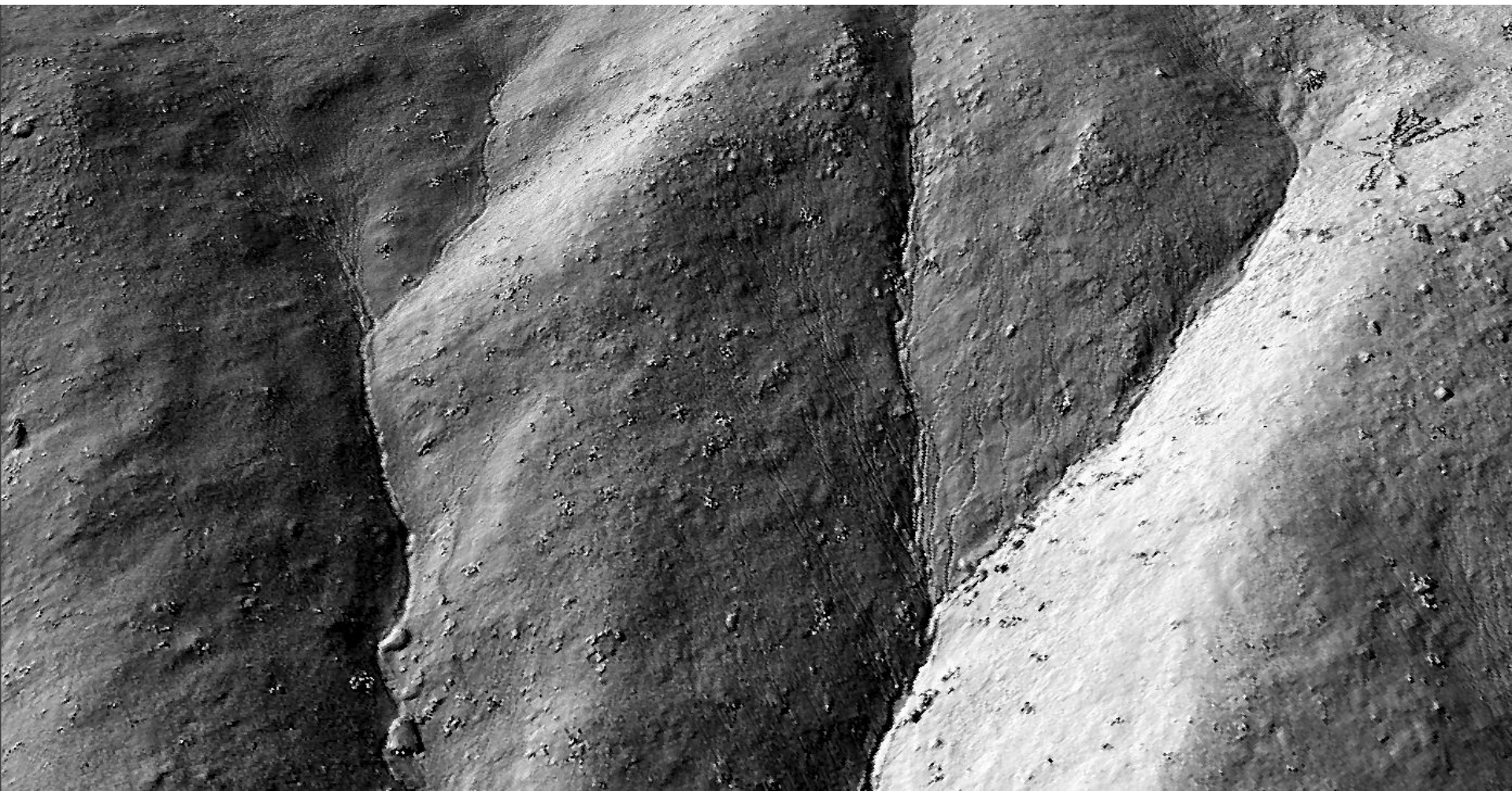












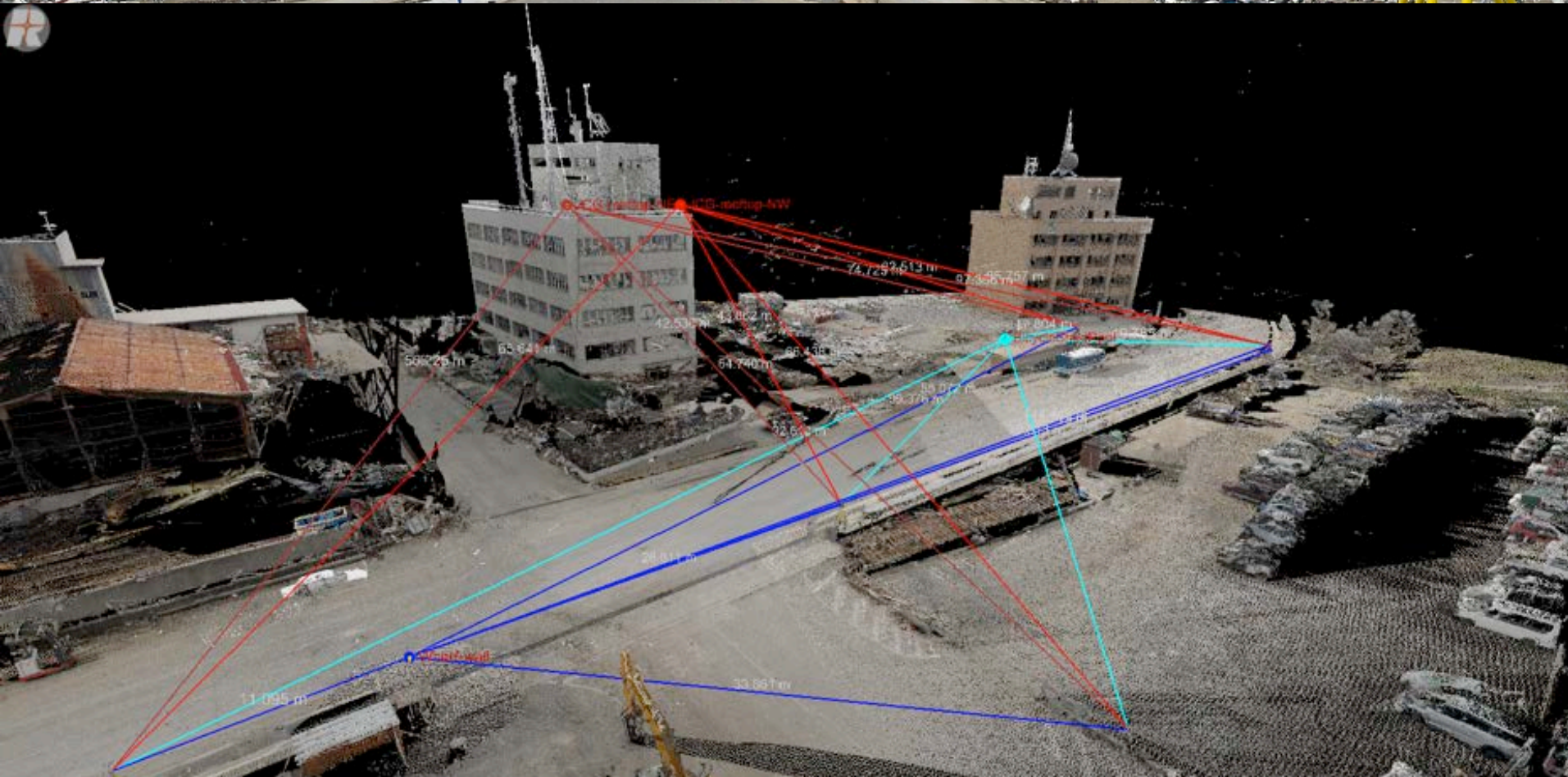


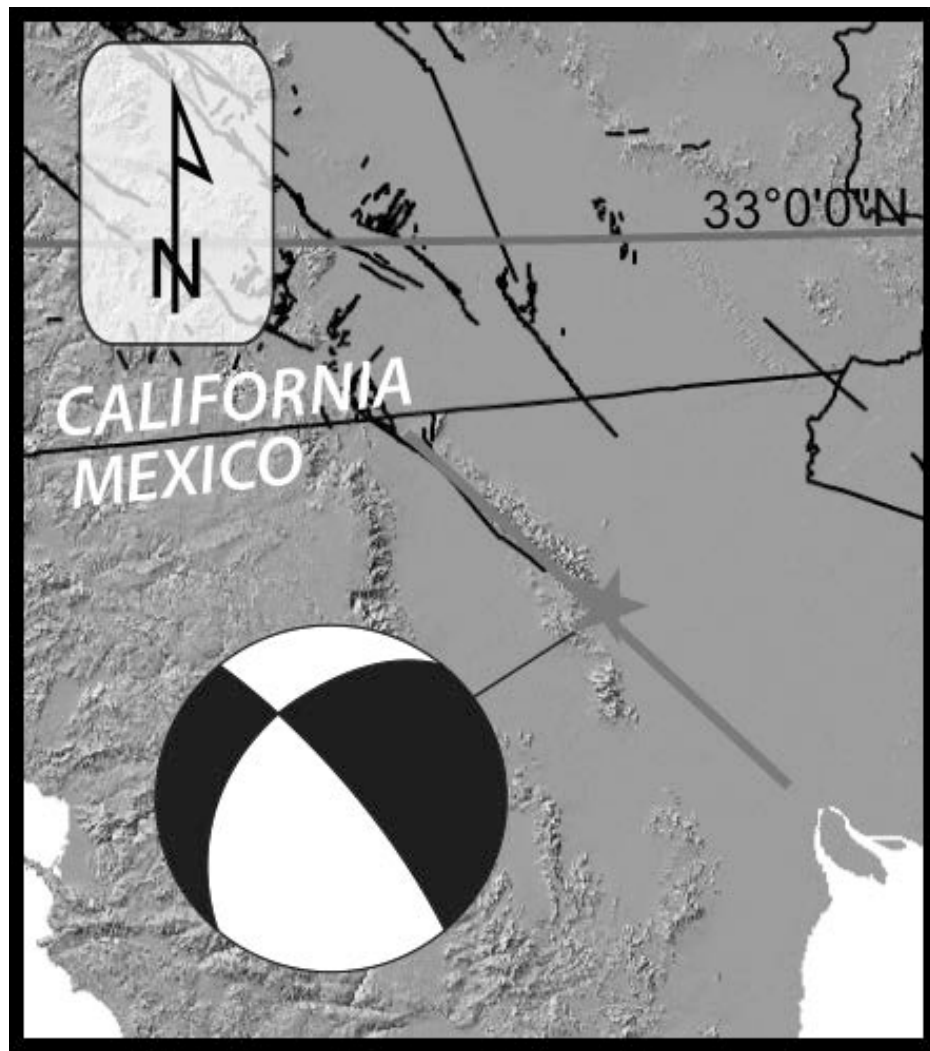
## Showcase Tool #1: TLS Terrestrial Laser Scanner



- Project: 2011 Japan Tsunami measurements
- PI: Hermann Fritz (Georgia Tech)
- NSF RAPID project

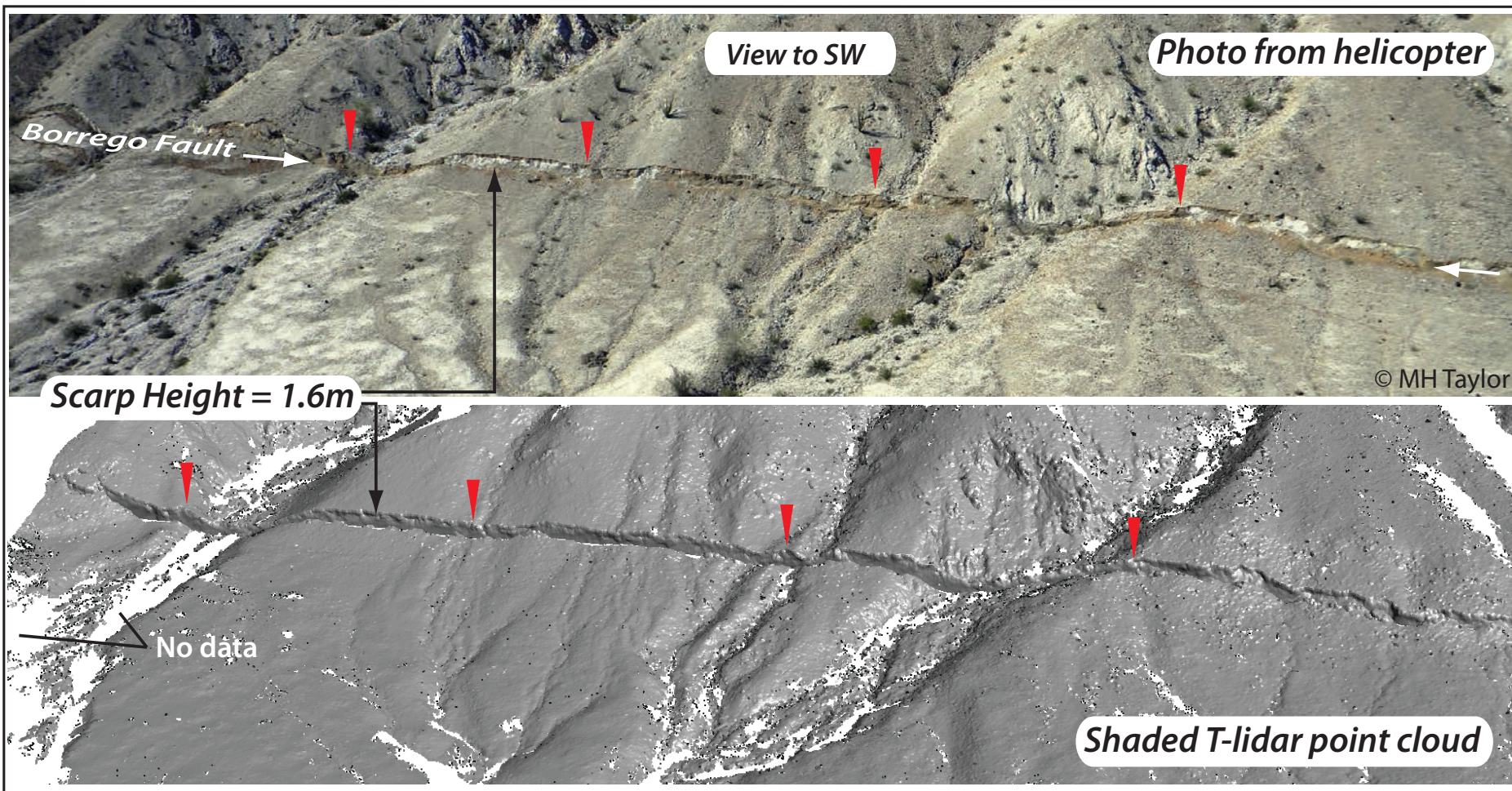






- April 4, 2010
- Mw 7.2
- ~100km rupture
- CA-Mexico border to the gulf
- > 3m right-normal slip north of epicenter
- < 1m right-normal blind faulting south of epicenter

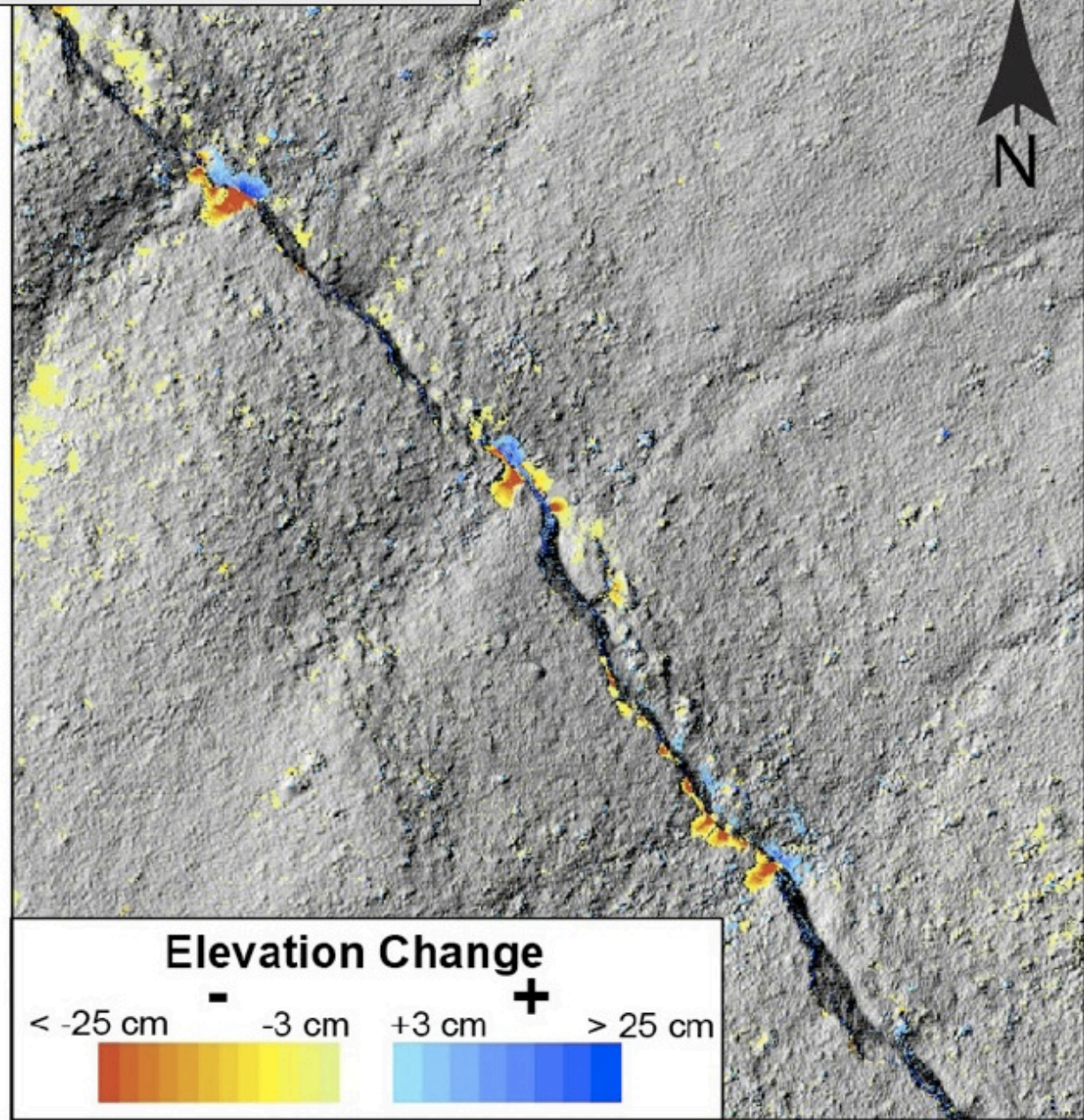
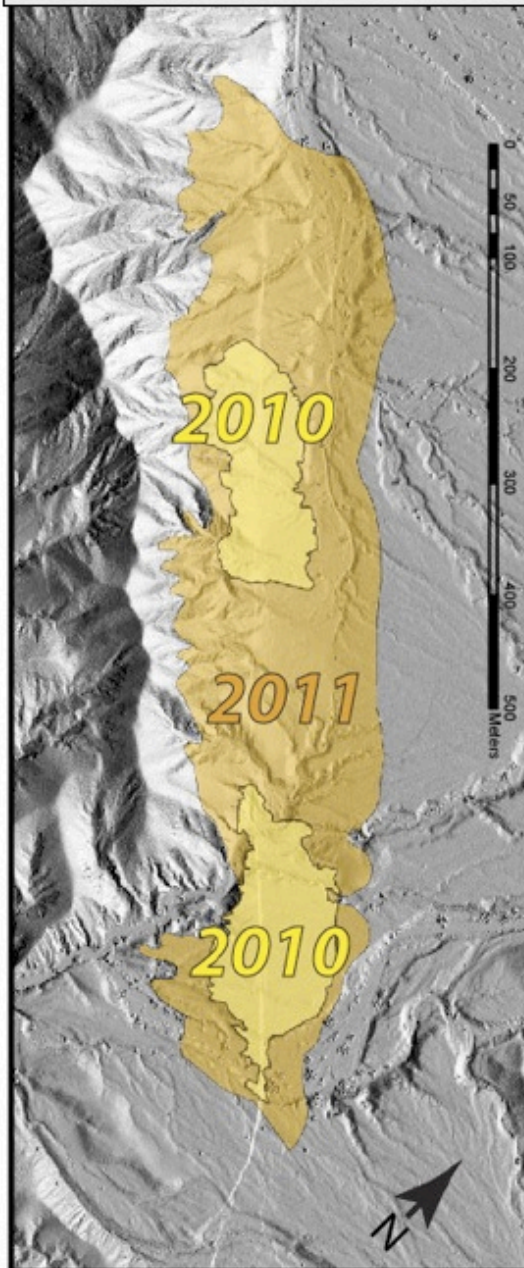




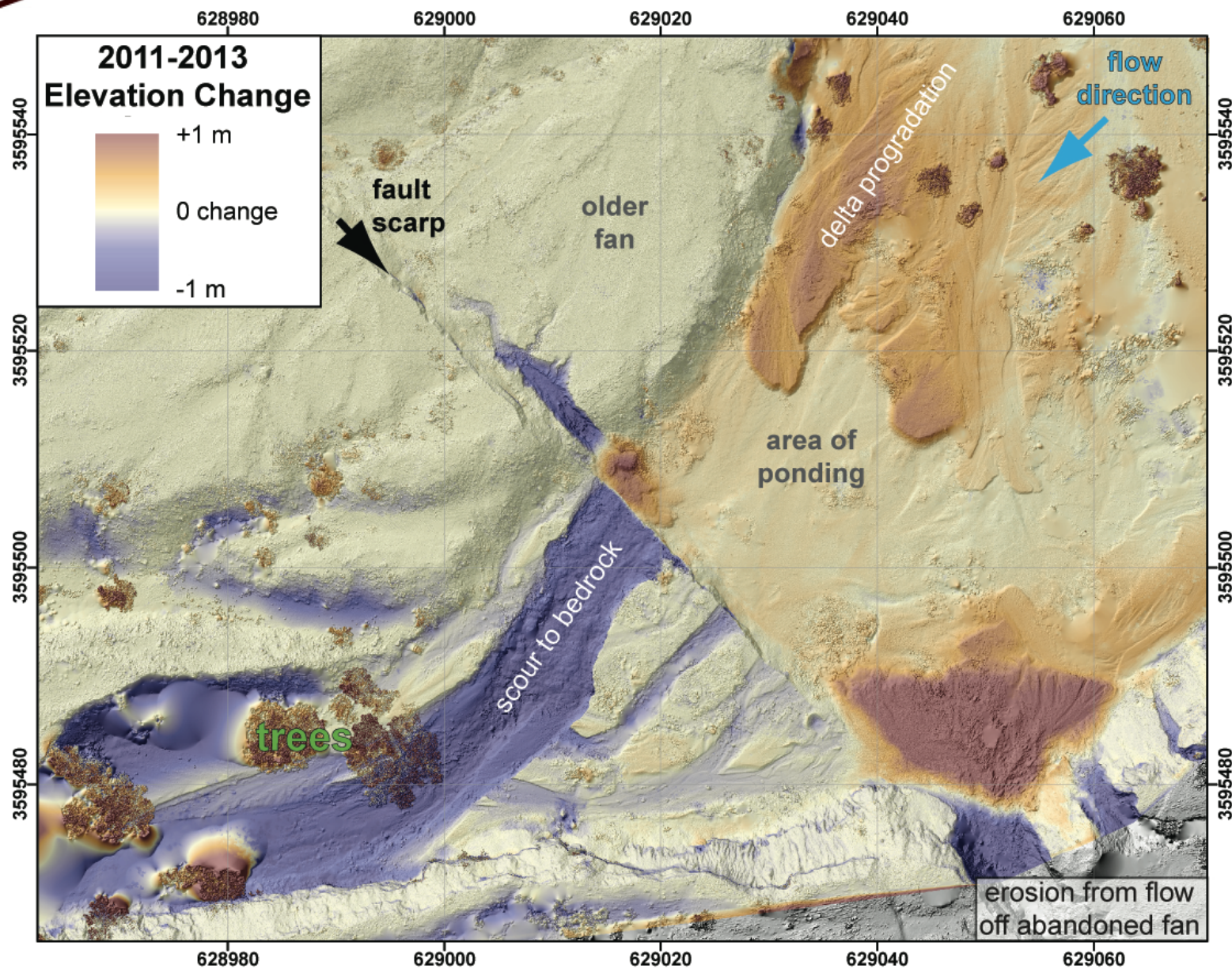


# Change Detection – Scarp Erosion

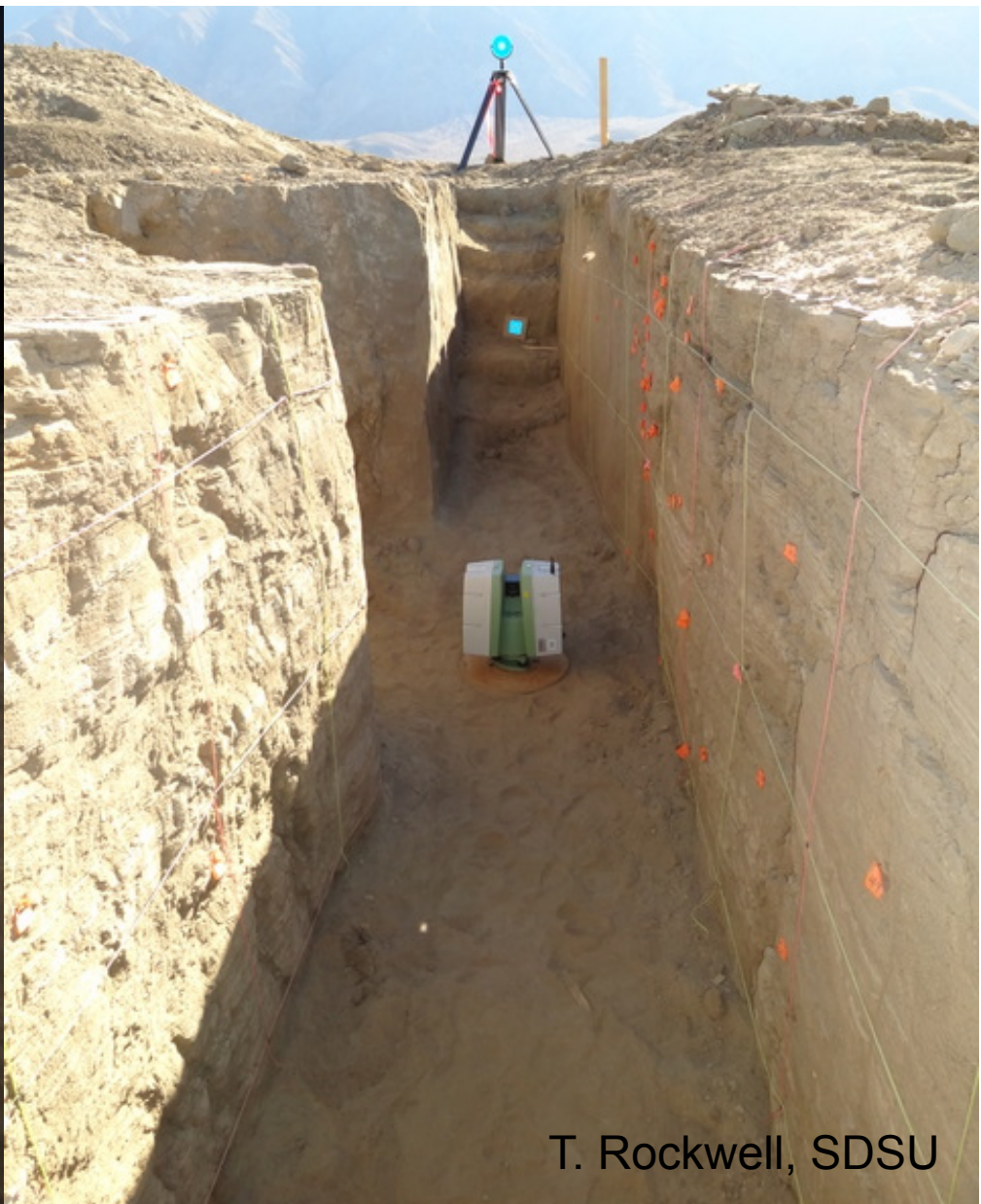
Austin Elliott (UC Davis Ph.D. student)





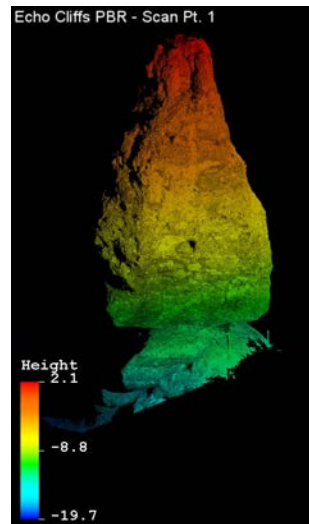
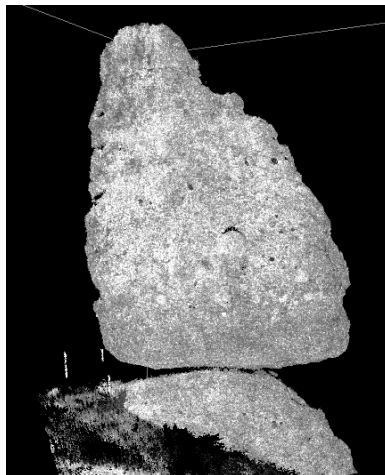








- Project Highlight: Precariously balanced rock (PBR) near Echo Cliffs, southern California.
- PI: Ken Hudnut, USGS.
- Goal: generate precise 3D image of PBR in order to calculate PBR's center of gravity for ground motion models useful for paleoseismology, urban planning, etc.



(Hudnut et al., 2009)







- 10–15 Antarctic and Arctic projects/year
- Remote locations, challenging logistics (helicopter, icebreaker, backpack)
- Extreme environmental conditions:
  - -35C to +15C, 20–65 knot winds

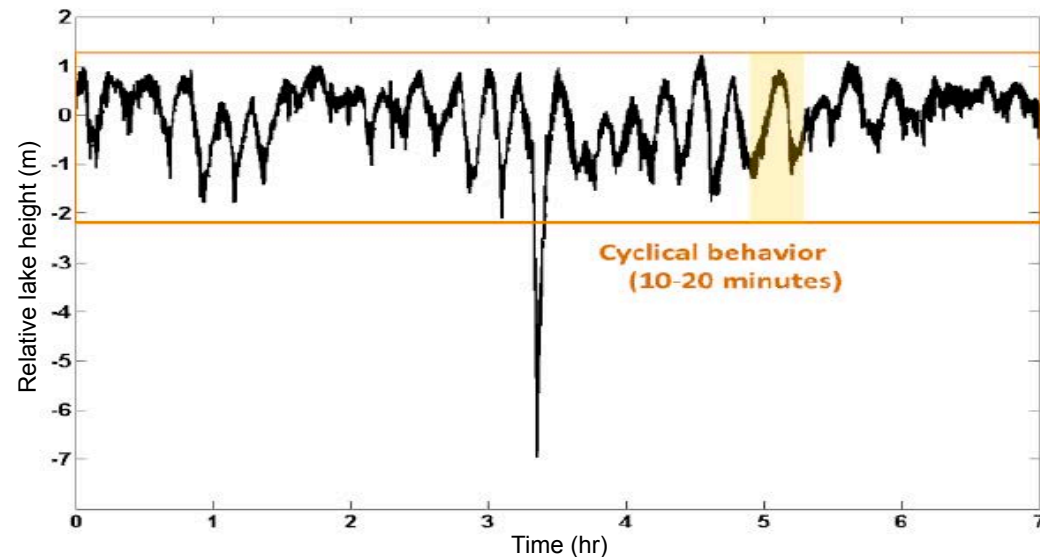
### Science:

- *Geomorphology*: Frost polygons and ancient lake beds
- *Glaciology*: Glacier melt and ablation
- *Biology/Ecology*: Weddell Seal volume; Microtopology of tundra in Alaska
- *Archaeology*: Human impact of climate change

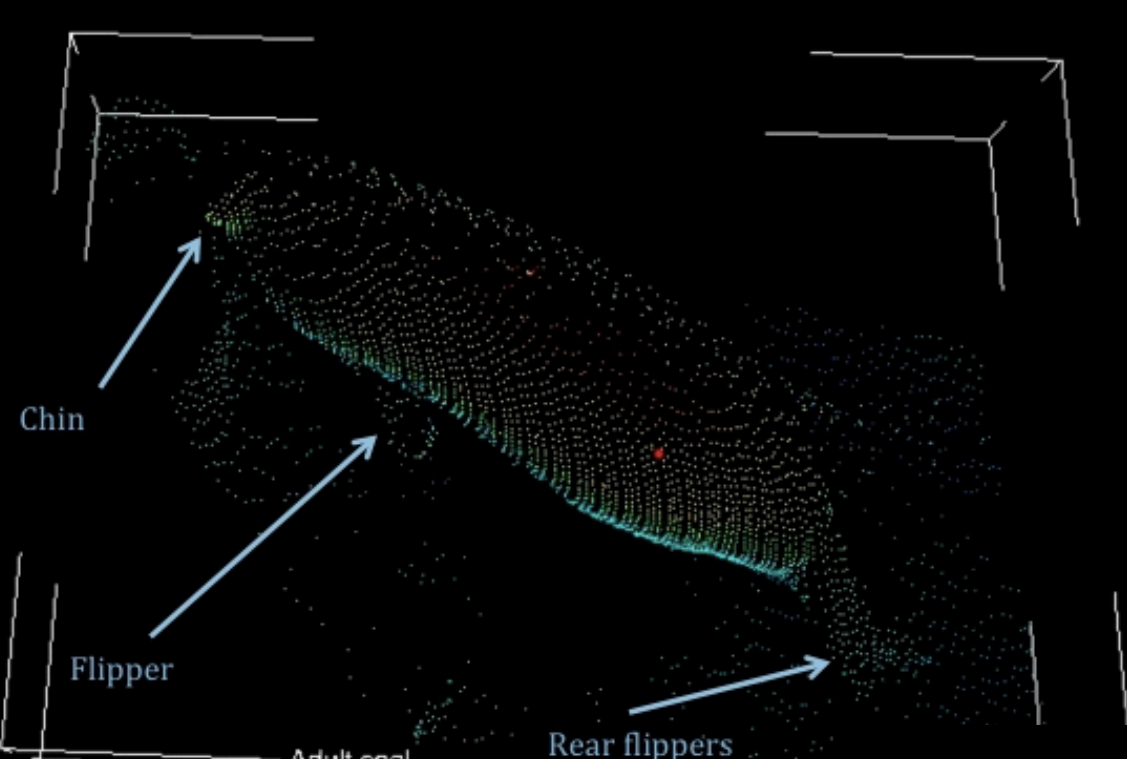


## Mount Erebus, Antarctica

- Lava lake scanned 2008–2013, revealing behaviors invisible to naked eye
- Inner crater scan used to augment and truth 2003 aerial scans
- Scans of ice caves and ice towers help determine thermal / energy budget of volcano

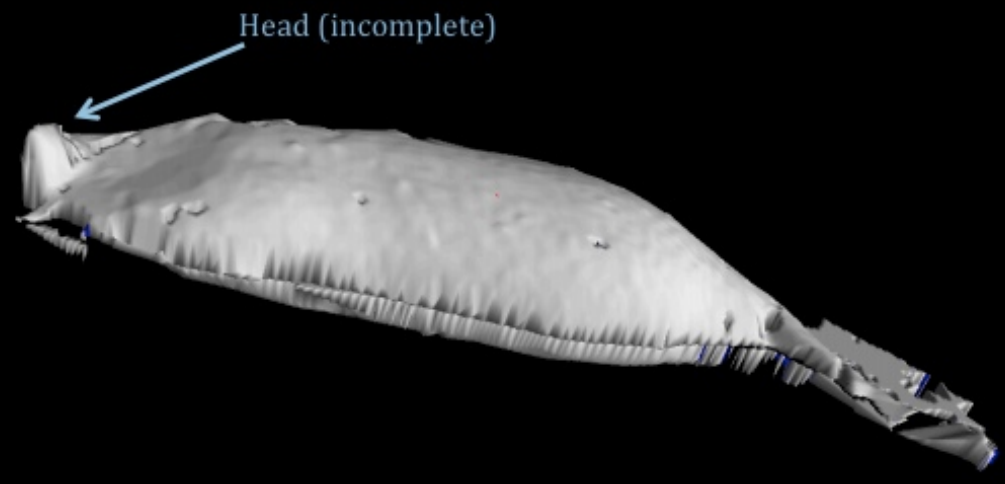






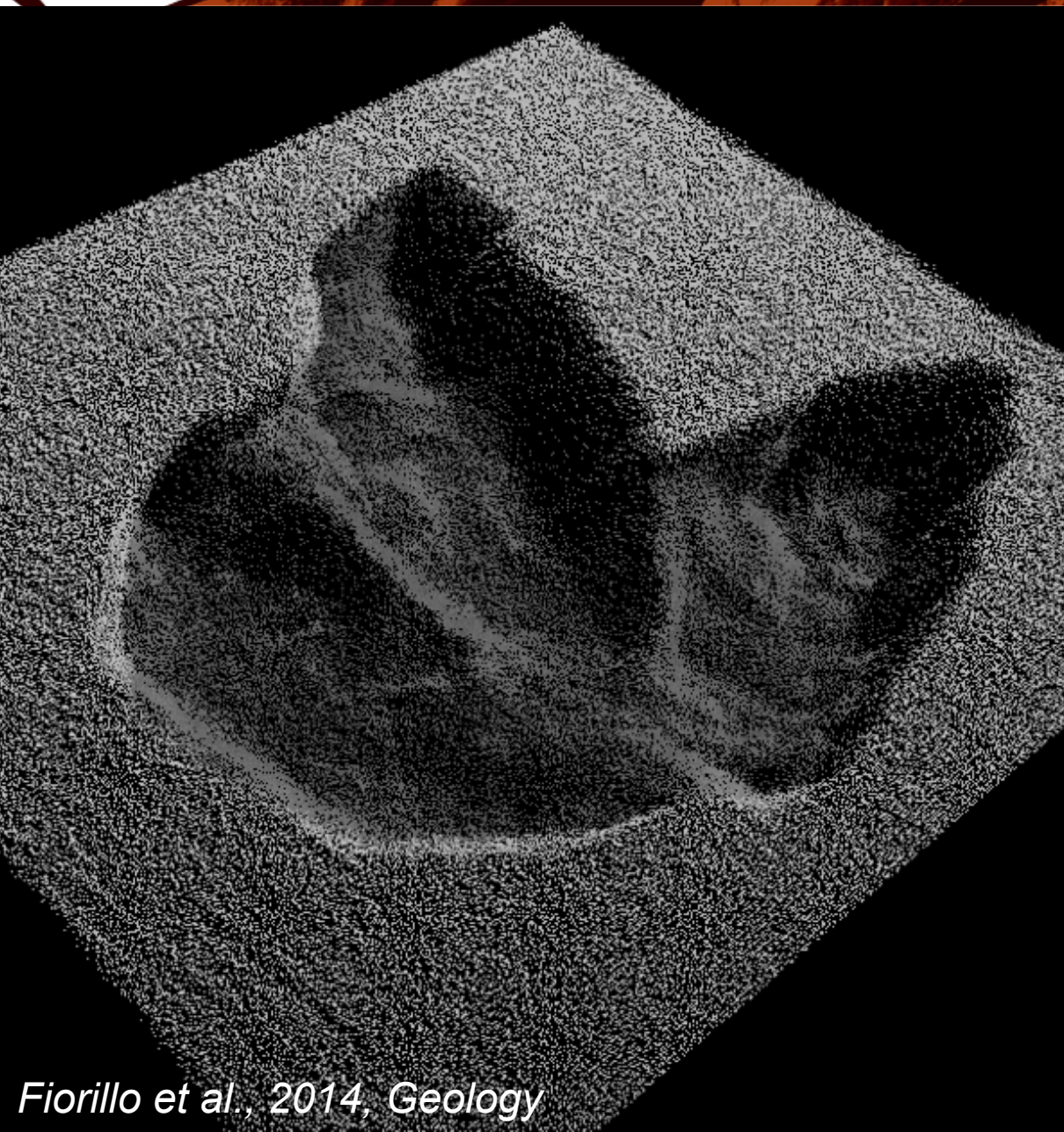
Using TLS to Obtain  
Volumetric  
Measurements of  
Weddell Seals in the  
McMurdo Sound

Seal body mass = proxy for  
availability of marine food  
resources

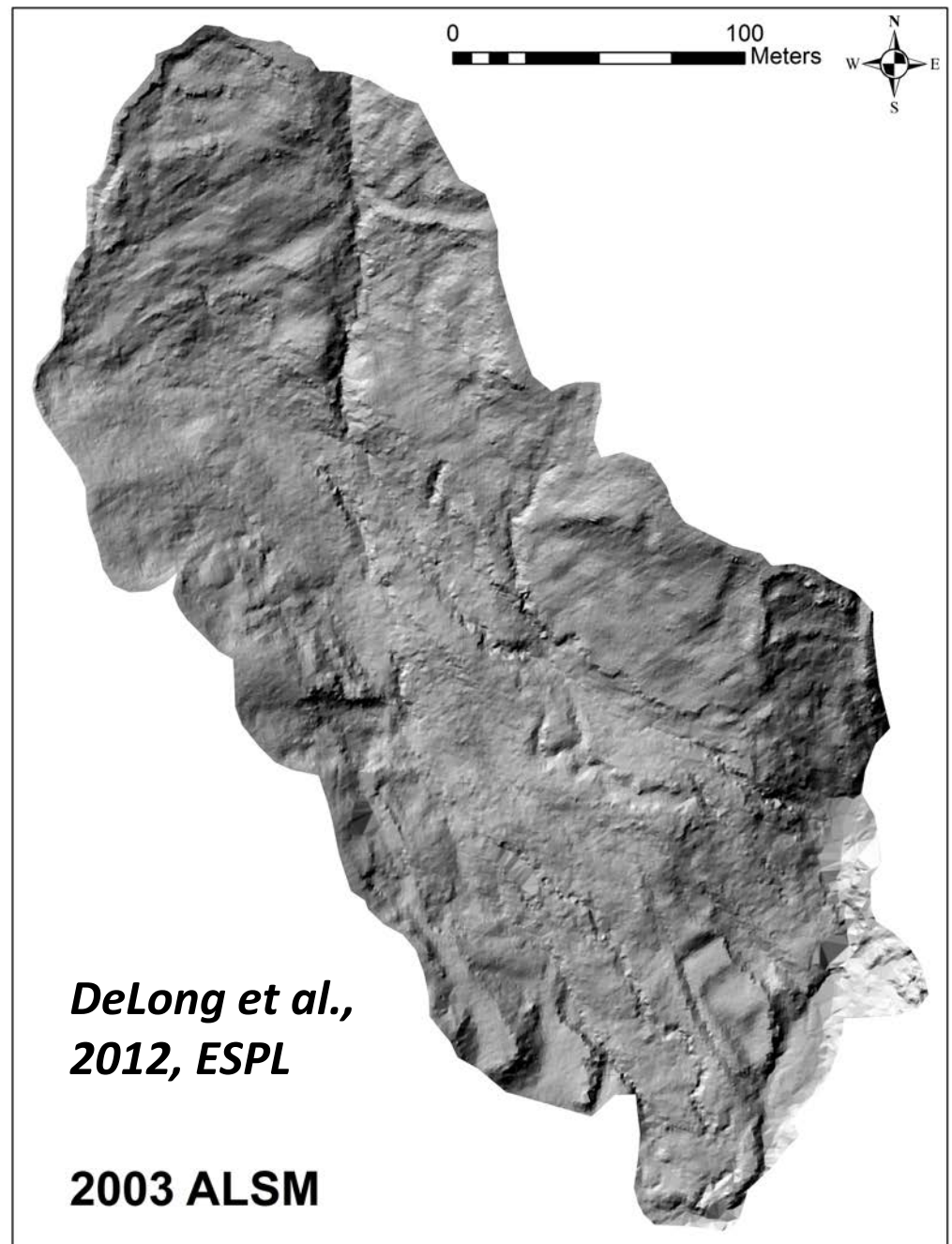
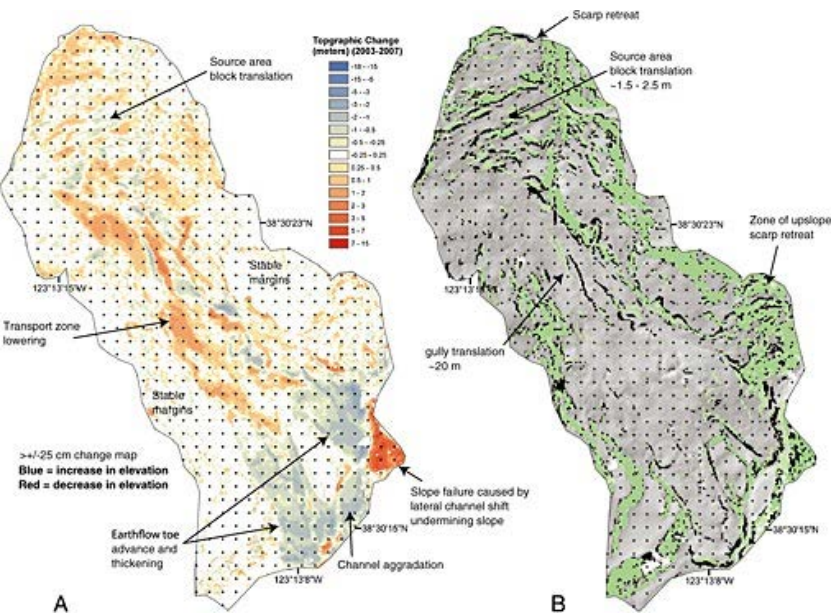




# Dinosaur Trackway, Denali National Park, AK





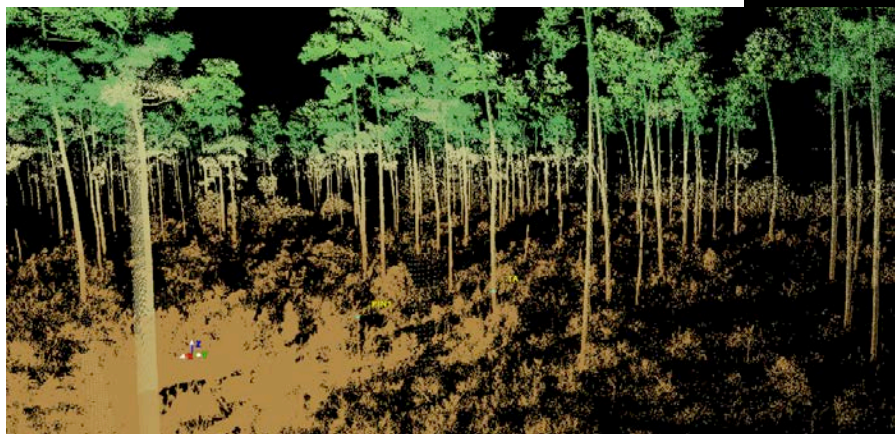
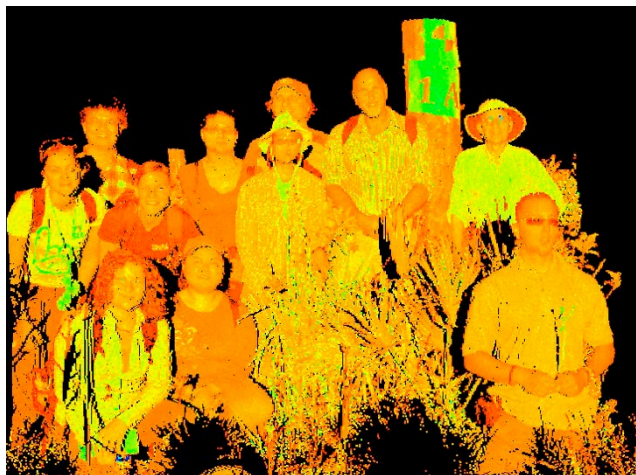




- Scanning to measure biomass in Everglades National Park (PI: Wdowinski).







*Thanks!*

***crosby@unavco.org***

***<http://unavco.org/tls>***



Photo: B. Hodge, UNAVCO – Location, RMNP